

Define $\det$ by the properties it possesses. Start with 3 axioms:

Axioms

- ① $\det$ depends linearly on the 1st row of matrix
- ② $\det$ changes sign when 2 rows are transposed
- ③ $\det(I) = 1$

using these together, $\det$ is linear in each row independently, not together
 $\det(A+B) \neq \det A + \det B$

④ Thm: If 2 rows of A are equal then $\det(A) = 0$
Let row $\vec{r}_i = \vec{r}_j$ Let $\det \begin{bmatrix} -\vec{r}_i \\ \vdots \\ \vec{r}_j \\ \vdots \end{bmatrix} = \beta$ Then by (2) $\det \begin{bmatrix} -\vec{r}_j \\ \vdots \\ \vec{r}_i \\ \vdots \end{bmatrix} = -\beta$
But $\vec{r}_i = \vec{r}_j$ so A is unchanged $\Rightarrow \beta = -\beta$ so $\beta = 0$ ie $\det(A) = 0$

⑤ Thm: Certain elementary row operations leave $\det$ unchanged.
[Those row ops given by an elementary matrix which is triangular with only 1s on main diag]

OK: $r_i \rightsquigarrow r_i \pm \alpha r_j$
NOT OK: $r_i \rightsquigarrow \alpha r_i \pm r_j$

The row that is being replaced must always have its own coeff equal to 1.

For the OK case, show it for row 1, row 2 in a tiny matrix. It then follows for any other 2 rows in a larger matrix by transposing them into r_1, r_2 position (Axiom 2), Do the elem operation, transpose them back to orig positions, (nullifying sign changes).

$$\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} \rightsquigarrow \det \begin{bmatrix} a & b \\ a-\alpha c & b-\alpha d \end{bmatrix} \stackrel{①}{=} \det \begin{bmatrix} a & b \\ c & d \end{bmatrix} - \alpha \det \begin{bmatrix} c & d \\ c & d \end{bmatrix} = \det A$$

0 by ④

For NOT OK case:

$$\det \begin{bmatrix} \alpha a + c & \alpha b + d \\ c & d \end{bmatrix} \stackrel{①}{=} \alpha \det \begin{bmatrix} a & b \\ c & d \end{bmatrix} + \det \begin{bmatrix} c & d \\ c & d \end{bmatrix} = \alpha \det(A)$$

0

So $\det A \neq \alpha \det A$ in general.

▷ There is an easy way to see this, if we anticipate Thm ⑨ and Thm ⑦ we can write row ops in terms of elementary matrices:

OK $A \rightsquigarrow EA$ $\begin{bmatrix} 1 & \alpha & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -\vec{r}_1 \\ -\vec{r}_2 \\ -\vec{r}_3 \end{bmatrix}$ $\det(EA) \stackrel{⑨}{=} \underbrace{\det E}_{1 \text{ by } ⑦} \cdot \det A$

E A

NOT OK

$$\begin{bmatrix} \alpha & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -\vec{r}_1 \\ -\vec{r}_2 \\ -\vec{r}_3 \end{bmatrix}$$

E A

here $\det E = \alpha \neq 1$ □

⑥ Thm A has $\vec{0}$ row $\Rightarrow \det A = 0$

Let A' be A with $\vec{0}$ row transposed to r_1 . Then $\det(A') = -\det A$ by ②
 $\det(A')$ is invariant under $r_1 \rightsquigarrow r_1 + r_2 = \vec{0} + r_2 = r_2$. Now A' has 2 rows equal to r_2
so $\det A' = 0$ by ④. Then $\det A = -0 = 0$ □

(2)

⑦ Thm If A is triangular then $\det(A) = a_{11} a_{22} \dots a_{nn}$ (product along main diag)

Idea:

pf. The det is invariant under back subs, so we can reduce it to a pure diag matrix, then use linearity to factor out each diag value: $\det A = (\prod a_{ii}) \det I$.
Finally we use axiom ③ that $\det I = 1$. More later.

$$\begin{bmatrix} a_{11} & * & * & * \\ & a_{22} & * & * \\ & & \ddots & * \\ 0 & & & a_{nn} \end{bmatrix}$$

▷ Let's step back and recap Gaussian elimination and Back Substitution from ch 1
[This will also be relevant when we get to Thm 10: $\det A = \det A^T$]

Following ch 1 p. 12 and 31 we do an easy case where no 0 pivots occur, no row exchanges nec.

$$A = \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \xRightarrow{\begin{matrix} E_1 \\ E_2 \end{matrix}} \begin{matrix} r_2 \rightarrow r_2 - 2r_1 \\ r_3 \rightarrow r_3 - r_1 \end{matrix} \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 8 & 3 \end{bmatrix} \xRightarrow{E_3} r_3 \rightarrow r_3 + r_2 \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix} = U$$

$$\text{we can represent this as } \underbrace{\begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix}}_{L^{-1}} \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix} = U$$

$$\text{Then } A = LU \quad \text{and} \quad L = E_1^{-1} E_2^{-1} E_3^{-1} = \begin{bmatrix} 1 & & \\ 2 & 1 & \\ & 1 & \end{bmatrix} \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} = \begin{bmatrix} 1 & & \\ 2 & 1 & \\ -1 & -1 & 1 \end{bmatrix} = L$$

Just flip the signs - that is easy trick that works only for elementary matrices!

So the triangular "A" that we have in Thm ⑦ is a "U". Only for the purpose of the pf of Thm ⑦, we continue with Elementary matrices to do Back Subs to make it diagonal.

$$U = \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{matrix} r_2 \rightarrow r_2 + 2r_3 \\ r_1 \rightarrow r_1 - r_3 \end{matrix} \begin{bmatrix} 2 & 1 & 0 \\ 0 & -8 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

I'm going to stop here because you get the idea - we can reduce the matrix to a diagonal one by elementary ops that do not change det.

▷ What about the case where we start with triangular A with a 0 on main diag? The back subs produces a 0 row, so $\det A = 0$ but this again follows from the product of main diag entries: $a_{11} a_{22} \dots 0 \dots a_{nn} = 0$

⑧ Thm A singular $\Rightarrow \det A = 0$
 A n.sing $\Rightarrow \det A \neq 0$

pf. If A sing, elimination will produce a $\vec{0}$ row (even if we did row interchanges) so $\det A = 0$ by ⑥ Thm.

If A n.sing, we can reduce to triangular U with all main diag entries (the pivots d_i) not equal 0. Thus $\det A = \pm d_1 d_2 \dots d_n \neq 0$ (+/- because maybe we needed to do row exchanges)

▷ To actually compute $\det(A)$ (for A bigger than 3×3), we reduce to U by Gaussian elim, keeping track of number of row exchanges. Then $\boxed{\det A = \pm \det U = \pm \prod d_i}$ □

⑨ Thm $\det(AB) = \det A \cdot \det B$ In particular $\det(AA^{-1}) = \det I = 1$ (3)

Pf. If A or B is sing, then AB is sing and $\det(AB) = 0$ $\det(A^{-1}) = \frac{1}{\det A}$

For A, B n.sing, define $d(A) := \frac{\det AB}{\det B}$ Show this satisfies Axioms ①, ②, ③.

Observe $\begin{bmatrix} a_1 & - \\ a_2 & - \\ a_3 & - \end{bmatrix} \begin{bmatrix} b_1 & b_2 & b_3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} a_1 b_1 & a_1 b_2 & a_1 b_3 \\ a_2 b_1 & a_2 b_2 & a_2 b_3 \\ a_3 b_1 & a_3 b_2 & a_3 b_3 \end{bmatrix} R$ (★)

$$d\left(\begin{bmatrix} \alpha a_1 + c \\ a_2 \\ a_3 \end{bmatrix}\right) = \frac{1}{\det B} \left(\det \left(\begin{bmatrix} \alpha a_1 + c \\ a_2 \\ a_3 \end{bmatrix} B \right) \right) = \frac{1}{\det B} \det \begin{bmatrix} (\alpha a_1 + c) b_1 & (\alpha a_1 + c) b_2 & (\alpha a_1 + c) b_3 \\ a_2 b_1 & a_2 b_2 & a_2 b_3 \\ a_3 b_1 & a_3 b_2 & a_3 b_3 \end{bmatrix} R$$

$$\stackrel{\text{Axiom ①}}{=} \frac{1}{\det B} \left(\alpha \det \begin{bmatrix} a_1 b_1 & a_1 b_2 & a_1 b_3 \\ a_2 b_1 & a_2 b_2 & a_2 b_3 \\ a_3 b_1 & a_3 b_2 & a_3 b_3 \end{bmatrix} + \det \begin{bmatrix} c b_1 & c b_2 & c b_3 \\ a_2 b_1 & a_2 b_2 & a_2 b_3 \\ a_3 b_1 & a_3 b_2 & a_3 b_3 \end{bmatrix} \right)$$

$$= \alpha d\left(\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}\right) + d\left(\begin{bmatrix} c \\ a_2 \\ a_3 \end{bmatrix}\right) \quad \text{linear in 1st row } \checkmark$$

▷ Transpose 2 rows:

$$d\left(\begin{bmatrix} a_2 \\ a_1 \\ a_3 \end{bmatrix}\right) = \frac{1}{\det B} \left(\det \begin{bmatrix} a_2 \\ a_1 \\ a_3 \end{bmatrix} \begin{bmatrix} b_1 & b_2 & b_3 \\ 1 & 1 & 1 \end{bmatrix} \right) = \frac{1}{\det B} \det \begin{bmatrix} a_2 b_1 & a_2 b_2 & a_2 b_3 \\ a_1 b_1 & a_1 b_2 & a_1 b_3 \\ a_3 b_1 & a_3 b_2 & a_3 b_3 \end{bmatrix}$$

compare with (★) and see this is 2 rows transposed in the prod

$$= - \frac{\det(AB)}{\det B} = -d(A)$$

▷ $d(I) = \frac{1}{\det B} \det(IB) = \frac{\det B}{\det B} = 1$

Thus $d(A)$ is a det, the unique det, so $d(A) = \det(A)$ Thus $\det(AB) = \det A \det B$ □

⑩ Thm $\det(A^T) = \det A$

If A is sing, then A^T is sing so $\det A = 0 = \det A^T$.

So assume now A n.sing. In the case no row exchanges needed, in ⑦ we showed $A = LU$. Here we want to make that LDU where the pivots are alone in a diag matrix, by factoring

$$U = \begin{bmatrix} d_1 & & \\ & d_2 & \\ & & d_3 \end{bmatrix} \begin{bmatrix} 1 & \frac{u_{12}}{d_1} & \frac{u_{13}}{d_1} \\ & 1 & \frac{u_{23}}{d_2} \\ & & 1 \end{bmatrix}$$

If A sing, $\exists x_0 \neq 0 \ni Ax_0 = 0$
 $\langle Ax_0, y \rangle = 0 \quad \forall y$

"
 $\langle x_0, A^T y \rangle = 0 \quad \forall y$

$\{x_0\}^\perp$ has dim $(n-1)$ but y is arb in n dim space

$\Rightarrow \exists x_0 \neq 0 \ni A^T x_0 = 0$

why is $\det P = \det P^T$?
 Perm matrix P is clearly O.N.
 so $P^T P = I$
 $\det P^T \det P = 1$ (★)

Since any P is attained by a series of row transpositions from I ,
 $\det P = +1$ or -1

If $\det P = +1$, $\det P^T = +1$ by (★)
 Likewise for $-1 \Rightarrow \det P = \det P^T$ □

▷ Now for the general case, we can account for row exchanges
 $PA = LDU \xrightarrow{\text{take det}} \det P \det A = \det L \det D \det U$

also for transpose $(PA)^T = (LDU)^T \Rightarrow A^T P^T = U^T D^T L^T$
 $\det A^T \det P^T = \det U^T \det D^T \det L^T$

$$\Rightarrow \det A^T \det P^T = \det D = \det P \det A \Rightarrow \det A^T = \det A$$

⑪ Thm A has EWs $\lambda_1, \dots, \lambda_n \Rightarrow \det A = \lambda_1 \lambda_2 \dots \lambda_n$

If we can diagonalize $A = S^{-1} \Lambda S$ $\det A = \det S^{-1} \det \Lambda \det S = \det(S S^{-1}) \det \Lambda = \det \Lambda$

If A has non-diag Jordan form, use Schur decomp to triangular matrix

□

We specified 3 axioms for the det fn, and we developed consequences of those axioms. But we did not prove such a fn actually exists. We don't know if doing row ops in a different order would produce a different value of det.

We shall derive the Leibniz sum-over-all-perms explicit expression for det. This will show it does exist and is well-defined.

By using the axioms we can derive a formula - then we can just take the formula and show it implies the axioms.

Consider 2x2 case use linearity of det. a row can be broken up
 $[a \ b] = [a \ 0] + [0 \ b]$

$$\det \begin{vmatrix} a & b \\ c & d \end{vmatrix} = \begin{vmatrix} a & 0 \\ c & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & d \end{vmatrix}$$

$$= \begin{vmatrix} a & 0 \\ c & 0 \end{vmatrix} + \begin{vmatrix} a & 0 \\ 0 & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & 0 \end{vmatrix} + \begin{vmatrix} 0 & b \\ 0 & d \end{vmatrix} = ad \begin{vmatrix} 1 & \\ & 1 \end{vmatrix} + bc \begin{vmatrix} & 1 \\ 1 & \end{vmatrix}$$

0 These dets are 0 because 0 col
 So the only survivors have 1 non-zero elt in each row & col
 any zero col eliminates that term

Generally this expansion would have n^n terms: n in 1st row, paired with n in 2nd row, etc...

How many terms survive?

$$n! = \frac{n}{\uparrow \text{choices for elt from 1st row}} \frac{(n-1)}{\uparrow \text{choices for elt from 2nd row}} \frac{(n-2)}{\uparrow \text{choices for elt from 3rd row}} \dots \frac{1}{\uparrow \text{choices for elt from nth row}}$$

This is the number of ways to perm n elts

Consider 3x3

Let's discuss the 3×3 expansion in more detail

$$\det \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = \overset{\sigma_e}{a_{11} a_{22} a_{33}} \begin{vmatrix} 1 & & \\ & 1 & \\ & & 1 \end{vmatrix} + \overset{\sigma_a}{a_{12} a_{23} a_{31}} \begin{vmatrix} 1 & & \\ & 1 & \\ & & 1 \end{vmatrix} + \overset{\sigma_b}{a_{13} a_{21} a_{32}} \begin{vmatrix} 1 & & \\ & 1 & \\ & & 1 \end{vmatrix} \\ + \overset{\sigma_c}{a_{11} a_{23} a_{32}} \begin{vmatrix} 1 & & \\ & 1 & \\ & & 1 \end{vmatrix} + \overset{\sigma_d}{a_{12} a_{21} a_{33}} \begin{vmatrix} 1 & & \\ & 1 & \\ & & 1 \end{vmatrix} + \overset{\sigma_f}{a_{13} a_{22} a_{31}} \begin{vmatrix} 1 & & \\ & 1 & \\ & & 1 \end{vmatrix}$$

$$= \sum_{\text{all } \sigma \in S_3} a_{1\sigma(1)} a_{2\sigma(2)} a_{3\sigma(3)} \det[P_\sigma]$$

σ is a perm of the cols. We can list them out $\sigma_e = \text{id}$

$$\text{sgn}(\sigma) = \begin{cases} +1 & \sigma \text{ is even \# of transp} \\ -1 & \text{odd} \end{cases}$$

$$\begin{aligned} \sigma_a(1) &= 2 \\ \sigma_a(2) &= 3 \\ \sigma_a(3) &= 1 \end{aligned}$$

This is $\begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$ and is achieved by 2 transposes $\{1, 2, 3\} \xrightarrow{(12)} \{3, 2, 1\} \xrightarrow{(12)} \{2, 3, 1\}$ (12) (13)
elts circled when in final position

Thus this is the product of 2 cycles $(12)(13)$
 $\text{sgn}(\sigma_a) = (-1)^2 = +1$

$$\begin{aligned} \sigma_b(1) &= 3 \\ \sigma_b(2) &= 1 \\ \sigma_b(3) &= 2 \end{aligned} \quad \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix} \quad \{1, 2, 3\} \xrightarrow{(12)} \{2, 1, 3\} \xrightarrow{(13)} \{3, 1, 2\}$$

$$(13)(12) \Rightarrow \text{sgn}(\sigma_b) = +1$$

$$\sigma_c = (23) \text{ transpose cols 2,3} \quad \text{sgn}(\sigma_c) = -1$$

$$\sigma_d = (12) \text{ cols 1,2} \quad \text{sgn}(\sigma_d) = -1$$

$$\sigma_f = (13) \quad \text{sgn}(\sigma_f) = -1$$

So we would like to say $\det(A) := \sum_{\text{all } \sigma \in S_n} a_{1\sigma(1)} \dots a_{n\sigma(n)} \det P_\sigma$

But we can't define $\det$ by referencing $\det$.

We need to understand the relationship between matrix P_σ and the perm σ (it is NOT the matrix rep of the perm, since P_σ has the columns permuted, not the rows).

Here it is: If we have a perm σ , we can represent it by a matrix Q_σ by applying σ to the rows of I . But here, we applied σ to the cols, thus $P_\sigma = (Q_\sigma)^T$

But this is no problem. The 3 axioms imply $\det(P) = \det P^T$

We must show $\det(P_\sigma) = \text{sgn}(\sigma)$

(2)

We must show $\det(P_\sigma) = \text{sgn}(\sigma)$

By the axioms, we perform row transposes on P_σ until it becomes I (this is the same as applying σ^{-1} to it) If it is accomplished in p transposes, then $\det(P_\sigma) = (-1)^p \det(I) = (-1)^p$

If n is large, different people might use different sets of transpositions to turn P_σ into I . But we have a theorem that perms consist of either an even or odd number of transposes, and no even perm can be achieved by odd # of transp and vice versa. See my sheets The Sym Group 10/9/2022

Therefore $\text{sgn}(\sigma)$ is well-defined and we can write

$$d(A) := \sum_{\sigma \in S_n} a_{1\sigma(1)} a_{2\sigma(2)} \cdots a_{n\sigma(n)} \text{sgn}(\sigma) \quad (\star)$$

▷ Now we must show d satisfies Axioms 1, 2, 3 so $d \equiv \det$ and thus $\det$ exists

(3) is the easiest $I = \begin{bmatrix} 1 & & \\ & \ddots & \\ & & 1 \end{bmatrix}$ then all terms are zero except
 $a_{11} a_{22} a_{33} \cdots a_{nn}$ and $\sigma(1)=1$
 $= 1 \cdot 1 \cdot 1 \cdots 1$ $\sigma(2)=2$ Id perm
 $= 1 \cdot \text{sgn}(\text{id})$ $\sigma(n)=n$
 $= 1$

(2) Let τ be a transposition, say $\tau = (2, 4) = \begin{pmatrix} 1 & 2 & 3 & 4 & \dots & n \\ 1 & 4 & 3 & 2 & \dots & n \end{pmatrix}$

We want to show $d(\tau A) = -d(A)$

$$d(\tau A) = \sum_{\sigma \in S_n} a_{1\sigma\tau(1)} a_{2\sigma\tau(2)} \cdots a_{n\sigma\tau(n)} \text{sgn}(\sigma\tau)$$

See my sheets
The Sym Group
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- $\sigma \circ \tau$ is just another elt of S_n so the sum $\sum_{\sigma \in S_n}$ stays the same
- $\text{sgn}(\sigma \circ \tau) = (-1) \text{sgn}(\sigma)$ since τ is a transposition
 we can write each σ as a product of transp - not unique, but the parity is invariant

$$\sigma = (\) (\) \cdots (\)$$

then $\sigma \circ \tau = (\) (\) \cdots (\) \underbrace{(2\ 4)}_{\tau}$ This adds 1 to the total and changes even $\rightarrow$ odd
 odd $\rightarrow$ even
 $\Rightarrow$ mult by -1

Cont'd $\rightarrow$

1/22/2026 (3)
 (1) To establish that d is linear in the 1st row, let's return to the expanded 3x3 case

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = \overset{+}{a_{11}} \overset{+}{a_{22} a_{33}} \overset{-}{a_{32} a_{23}} + \overset{+}{a_{12}} \overset{-}{a_{23} a_{31}} \overset{+}{a_{31} a_{21}} + \overset{-}{a_{13}} \overset{+}{a_{21} a_{32}} \overset{-}{a_{32} a_{21}} \\ + \overset{-}{a_{11}} \overset{-}{a_{23} a_{32}} \overset{+}{a_{32} a_{21}} + \overset{+}{a_{12}} \overset{+}{a_{21} a_{33}} \overset{-}{a_{31} a_{23}} + \overset{-}{a_{13}} \overset{-}{a_{23} a_{31}} \overset{+}{a_{31} a_{21}}$$

This shows how we can factor out the terms from the first row

$$\det(A) = a_{11} Q_{11} + a_{12} Q_{12} + \dots + a_{1n} Q_{1n} \quad \text{LC of elts of 1st row}$$

If $\vec{a}_1 = \vec{b}_1 + \lambda \vec{c}_1$, row vectors

$$\begin{aligned} d \begin{bmatrix} -b_1 + \lambda c_1 \\ -a_2 \\ \vdots \\ -a_n \end{bmatrix} &= (b_{11} + \lambda c_{11}) Q_{11} + \dots + (b_{1n} + \lambda c_{1n}) Q_{1n} \\ &= b_{11} Q_{11} + \lambda c_{11} Q_{11} + \dots + b_{1n} Q_{1n} + \lambda c_{1n} Q_{1n} \\ &= d \begin{bmatrix} -b_1 \\ -a_2 \\ \vdots \\ -a_n \end{bmatrix} + \lambda d \begin{bmatrix} -c_1 \\ -a_2 \\ \vdots \\ -a_n \end{bmatrix} \end{aligned}$$

QED

▷ Now we need to establish Laplace's Cofactor Expansion

Let's show it for a 3x3, let's expand along the 1st col by linearity

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & a_{32} & a_{33} \end{vmatrix} + \begin{vmatrix} 0 & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ 0 & a_{32} & a_{33} \end{vmatrix} + \begin{vmatrix} 0 & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$$

M_{11}

Transpose the nonzero elts to the top

$$(-1) \begin{vmatrix} a_{21} & a_{22} & a_{23} \\ 0 & a_{12} & a_{13} \\ 0 & a_{32} & a_{33} \end{vmatrix} + (-1)^2 \begin{vmatrix} a_{31} & a_{32} & a_{33} \\ 0 & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \end{vmatrix}$$

M_{21} M_{31}

We shall show later that

if matrix A is block upper triang

$$A = \begin{bmatrix} B & C \\ 0 & D \end{bmatrix} \quad \det A = \det B \det D$$

Block M_{ij} is A missing row i and col j

Since $\det A = \det(A^T)$

We can expand down any row or column.

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$$\Rightarrow \det(A) = a_{11} \det M_{11} + a_{21} (-1) \det M_{21} + a_{31} (-1)^2 \det M_{31}$$

Fix row i

$$\det(A) = \sum_{j=1}^n a_{ij} \underbrace{(-1)^{i+j} \det(M_{ij})}_{\text{Cofactor } C_{ij}}$$

The signs of the Cofactors are given by a checkboard pattern:

$$\begin{bmatrix} + & - & + & - & + \\ - & + & - & + & - \\ + & - & + & - & + \\ - & + & - & + & - \\ + & - & + & - & + \end{bmatrix} (-1)^{i+j}$$

Computation of A^{-1} Expand $\det A$ in cofactors along row i

$$(*) \quad \det A = a_{i1} C_{i1} + \dots + a_{in} C_{in}$$

If this 2nd index would be const, we are expanding down col j of A

We can write this as matrix mult if we make a Cofactor matrix by putting the above cofactors in the columns (so I call it C^T)

If the 1st index is const (row i), we are expanding down that row, and that is where the a s are expected to come from

Let's show it in 3×3 case:

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} C_{11} & C_{21} & C_{31} \\ C_{12} & C_{22} & C_{32} \\ C_{13} & C_{23} & C_{33} \end{bmatrix} = \begin{bmatrix} \det A & 0 & 0 \\ 0 & \det A & 0 \\ 0 & 0 & \det A \end{bmatrix}$$

$A \qquad C^T$

(*) gives us the main diag terms. But why should off diag terms be 0? [Illustrate for this term]

$$a_{11} C_{21} + a_{12} C_{22} + a_{13} C_{23} \stackrel{?}{=} 0$$
Recall cofactor expansion for 1st row:

$$\det A = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} + (-1) a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + (-1)^2 a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

Now explicitly show cofactors C_{21}, C_{22}, C_{23} so transpose row 2 and row 1 and expand:

$$\det A = (-1) \begin{vmatrix} a_{21} & a_{22} & a_{23} \\ a_{12} & a_{13} & a_{11} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = (-1) a_{21} \begin{vmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{vmatrix} + (-1)^2 a_{22} \begin{vmatrix} a_{11} & a_{13} \\ a_{31} & a_{33} \end{vmatrix} + (-1)^3 a_{23} \begin{vmatrix} a_{11} & a_{12} \\ a_{31} & a_{32} \end{vmatrix}$$

$C_{21} \qquad C_{22} \qquad C_{23}$

If we now plugged in the row 1 elts as I have written them in blue that would mean the RHS came from expansion of a matrix with a duplicate row

$$0 = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{11} & a_{12} & a_{13} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11} C_{21} + a_{12} C_{22} + a_{13} C_{23} \quad \checkmark$$

Thus $A C^T = (\det A) I$

Strang calls C^T ' A_{cof} '

$$A \left[\frac{1}{\det A} C^T \right] = I$$

or $A \left[\frac{1}{\det A} A_{\text{cof}} \right] = I$

Thus $A^{-1} = \frac{1}{\det A} A_{\text{cof}}$

So for 2×2

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

□

Thm Cramer's Rule x is sol'n to $Ax=b \Rightarrow x^{(j)} = \frac{\det B_j}{\det A}$ where $B_j = \begin{bmatrix} \vec{a}_1 & \vec{a}_2 & \dots & \vec{b} & \dots & \vec{a}_n \end{bmatrix}$
 replace col $\vec{a}_j$ by $\vec{b}$

Pf. $Ax=b \Rightarrow x = A^{-1}b = \frac{1}{\det A} A_{\text{adj}} b$

$\triangleright x^{(j)}$ is the j^{th} component in $A_{\text{adj}} b$

Let's write it out in the 3×3 case:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \frac{1}{\det A} \begin{bmatrix} c_{11} & c_{21} & c_{31} \\ c_{12} & c_{22} & c_{32} \\ c_{13} & c_{23} & c_{33} \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

Let's just take $j=2$

$$(\det A) x_2 = b_1 c_{12} + b_2 c_{22} + b_3 c_{32} \quad (\star)$$

$\triangleright$ On the other hand, expanding $\det A$ down col 2 $\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{12}c_{12} + a_{22}c_{22} + a_{32}c_{32}$
 If we had replaced col 2 by $\vec{b}$

$$b_1 c_{12} + b_2 c_{22} + b_3 c_{32} = \begin{vmatrix} a_{11} & b_1 & a_{13} \\ a_{21} & b_2 & a_{23} \\ a_{31} & b_3 & a_{33} \end{vmatrix} = \det B_2$$

$\triangleright$ Thus $(\star)$ becomes $(\det A) x_2 = \det B_2$
 $x_2 = \frac{1}{\det A} \det B_2$

