

Real OG (i.e. ON) matrices, Hermitian, skew-Herm, Unitary, Perms, etc... all belong to the class of Normal Matrices

Def A is normal if  $A^H A = AA^H$  (commutes with its herm)

We shall follow the discussion in Horn & Johnson MA p. 101 which encompasses all Strang's examples. Let A be  $n \times n$  matrix with EWs  $\lambda_1, \dots, \lambda_n$  (not nec distinct).

Thm TFAE

(a) A is normal:  $A^H A = AA^H$

(b) A can be diagonalized by unitary  $U^H AU = \Lambda$

$$\sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 = \sum |\lambda_i|^2$$

(d)  $\exists$  ON set of n EVs of A

Pf. Step 1 Given A, from Schur's Lemma  $\exists$  triangular T and unitary U  $\exists U^H AU = T$

A normal  $\Rightarrow$  T normal

$$TT^H = U^H AU (U^H AU)^H = U^H A U U^H U^H A^H U \stackrel{\text{A norm}}{\downarrow} = U^H A^H A U \\ = U^H A^H U U^H A U \\ = (U^H A U)^H U^H A U = T^H T$$

The plan is to show (a)  $\Leftrightarrow$  (b)

and (b)  $\Leftrightarrow$  (c)  
 $\Leftrightarrow$  (d)

Step 2 (a)  $\Rightarrow$  (b)

We established A normal  $\Rightarrow$  T normal i.e.  $T^H T = T T^H$

Now show this cond forces T to actually be diag.

[A normal triag matrix is, in fact, diag.]

Writing out an example makes this clear:

$$\begin{matrix} T^H \\ \begin{bmatrix} \bar{t}_{11} & 0 & 0 & 0 \\ \bar{t}_{12} & \bar{t}_{22} & 0 & 0 \\ \bar{t}_{13} & \bar{t}_{23} & \bar{t}_{33} & 0 \\ \bar{t}_{14} & \bar{t}_{24} & \bar{t}_{34} & \bar{t}_{44} \end{bmatrix} \end{matrix} \begin{matrix} T \\ \begin{bmatrix} t_{11} & t_{12} & t_{13} & t_{14} \\ & t_{22} & t_{23} & t_{24} \\ & t_{33} & t_{34} & \\ & t_{44} & & \end{bmatrix} \end{matrix} = \begin{matrix} T \\ \begin{bmatrix} t_{11} & t_{12} & t_{13} & t_{14} \\ & t_{22} & t_{23} & t_{24} \\ & t_{33} & t_{34} & \\ & t_{44} & & \end{bmatrix} \end{matrix} \begin{matrix} T^H \\ \begin{bmatrix} \bar{t}_{11} & \bar{t}_{12} & \bar{t}_{13} & \bar{t}_{14} \\ \bar{t}_{12} & \bar{t}_{22} & \bar{t}_{23} & \bar{t}_{24} \\ \bar{t}_{13} & \bar{t}_{23} & \bar{t}_{33} & \bar{t}_{34} \\ \bar{t}_{14} & \bar{t}_{24} & \bar{t}_{34} & \bar{t}_{44} \end{bmatrix} \end{matrix}$$

Comparing the (1,1) elt on both sides, we see all terms in 1<sup>st</sup> row above main diag must be 0

$$\bar{t}_{11} t_{11} \stackrel{!}{=} t_{11} \bar{t}_{11} + \sum_{j=2}^n t_{1j} \bar{t}_{1j} = |t_{11}|^2 + \underbrace{\sum_{j=2}^n |t_{1j}|^2}_{\text{LHS}}$$

This must be 0 to equal LHS

But since each term is non-neg, each term must be 0  $\Rightarrow$  only  $t_{11}$  is nonzero in 1<sup>st</sup> row

[In fact, we know  $t_{11} = \text{EW } \lambda_1$ ]

(Cont'd →)

Now look at the  $(2,2)$  term:

$$\begin{bmatrix} \bar{t}_{11} & 0 & 0 & 0 \\ 0 & \bar{t}_{22} & & \\ 0 & \bar{t}_{23} & \bar{t}_{33} & \bar{t}_{34} \\ 0 & \bar{t}_{24} & \bar{t}_{34} & \bar{t}_{44} \end{bmatrix} \begin{bmatrix} t_{11} & 0 & 0 & 0 \\ t_{22} & t_{23} & t_{24} & \\ t_{33} & t_{34} & t_{44} & \\ t_{44} & & & \end{bmatrix} = \begin{bmatrix} t_{11} & 0 & 0 & 0 \\ t_{22} & t_{23} & t_{24} & \\ t_{33} & t_{34} & t_{44} & \\ t_{44} & & & \end{bmatrix} \begin{bmatrix} \bar{t}_{11} & & & \\ 0 & \bar{t}_{22} & & \\ 0 & \bar{t}_{23} & \bar{t}_{33} & \\ 0 & \bar{t}_{24} & \bar{t}_{34} & \bar{t}_{44} \end{bmatrix}$$

$$\bar{t}_{22} t_{22} = t_{22} \bar{t}_{22} + \sum_{j=3}^n t_{2j} \bar{t}_{2j}$$

by same arg, each term in this sum is 0

By working down the diag elts  $(3,3), \dots, (n,n)$  we see each row is 0 off main diag and thus  $T = \Lambda$  [we already know from Schur diag elts are EWs].

Step 3 (a)  $\Leftrightarrow$  (b)

Obviously diag  $\Lambda$  is normal:  $\Lambda^H \Lambda = \Lambda \Lambda^H$

Thus  $U^H A U = \Lambda \Rightarrow A$  is normal by similar arg as Step 1.

Step 4 (b)  $\Leftrightarrow$  (c) cl an skipping this. The calculation would make more sense in the context of matrix norms. Cf Atkinson ATNA p. 415-421 and prob 22 p. 431

Step 5 (b)  $\Leftrightarrow$  (d)

$U^H A U = \Lambda \Leftrightarrow A U = U \Lambda$  the cols of  $U$  are the full set of O.N. EWs.  $\square$

► Jordan Form of matrix (Jordan Normal Form - no relation to prev word 'normal')

If  $A$  has full set of EVs, we can diagonalize  $A S = S \Lambda$

$$\underbrace{\Lambda}_{J} = S^{-1} A S$$

What if  $A$  does not have a full set?  
How close to diagonal can we make it?

Jordan form thm If  $A$  has  $p \leq n$  indep EWs

$$\Rightarrow \exists \text{ C.O.B. } M \ni M^{-1} A M = J =$$

$$\begin{bmatrix} J_1 & & & \\ & J_2 & & \\ & & \ddots & \\ & & & J_p \end{bmatrix}$$

Each  $J_i$  block has only a single EW  $\lambda_i$  and 1s above the main diag of  $J_i$  and is associated with only 1 EV  $J_i = \begin{bmatrix} \lambda_i & 1 & & 0 \\ & \lambda_i & 2 & \\ & & \ddots & \\ & & & \lambda_i \end{bmatrix}$

[a value  $\lambda_i$  can appear in more than 1 Jordan block if it matches to more than 1 EV - see examples to follow]

2 matrices are similar  $\Leftrightarrow$  they have same JNF

$J$  is unique up to ordering of blocks  
a convention is to write them in decreasing size

cl worked through the pf in Schuams LA ch 10

Here I will just give some examples:

$$\textcircled{1} \quad \text{consider } T = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \quad A = \begin{bmatrix} 2 & -1 \\ 1 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

all share  $J = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$  That means 2 EVs  $\lambda_1 = 1 = \lambda_2$  and 1 EV

$$\text{For } T \quad M^{-1}TM = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = J$$

$$\text{For } B \quad \text{we can do it with a perm matrix (accomplish transpose to } J) \quad P^{-1}BP = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = J$$

For A they don't give calculation, just say by Stur Lemma,  $\exists U \ni U^{-1}AU = T$  and we already did T.

$$\textcircled{2} \quad A = \begin{bmatrix} 0 & 1 & 2 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \lambda = 0 \text{ is a triple EW for both - look at the main diag since both triangular}$$

$$\text{The possible Jordan forms are } J = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \text{ or } J = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \text{ or } J = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

1 EV                          2 EVs                          3 EVs  
(or  $\infty$  EVs)

$$\text{For A, there is only 1 EV: } A \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = 0 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\text{Thus its Jordan form must be the } J \text{ with only 1 block. } J = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{For B there are 2 EVs for } \lambda = 0 \quad \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \Rightarrow J \text{ has 2 blocks, must be } \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

But this counting trick only works when nothing more than a triple EW

**Prob 5.6.31** Write out all  $(4 \times 4)$  J forms of a  $4 \times 4$  matrix with quad  $\lambda = 0$ :

By convention we start with largest block and decrease down main diag

$$\begin{bmatrix} 0 & 1 & & \\ 0 & 0 & 1 & \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \text{ or } \begin{bmatrix} 0 & 1 & & \\ 0 & 0 & 1 & \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \text{ or } \begin{bmatrix} 0 & 1 & & \\ & 0 & 1 & \\ & 0 & 0 & 1 \\ & 0 & 0 & 0 \end{bmatrix} \text{ or } \begin{bmatrix} 0 & 1 & & \\ & 0 & 1 & \\ & 0 & 0 & 1 \\ & 0 & 0 & 0 \end{bmatrix} \text{ or } \begin{bmatrix} 0 & 0 & & \\ 0 & 0 & 1 & \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

1 EV                          2 EVs                          3 EVs                          4 EVs  
( $\infty$  EVs)

So if 2 EVs, there are 2 choices for J and a priori we don't know.

(15)

example from Schuam's LA ch 9 prob 9.8 p. 206-207

$$A = \begin{bmatrix} 1 & -3 & 3 \\ 3 & -5 & 3 \\ 6 & -6 & 4 \end{bmatrix}$$

$$B = \begin{bmatrix} -3 & 1 & -1 \\ -7 & 5 & 1 \\ -6 & 6 & -2 \end{bmatrix}$$

Characteristic poly

$$\Delta(\lambda) = (\lambda+2)^2(\lambda-4)$$

$$\Delta(\lambda) = (\lambda+2)^2(\lambda-4) \text{ same poly, same EWs}$$

But different EVs

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$$J = \begin{array}{|c|c|} \hline -2 & & \\ \hline & -2 & \\ \hline & & 4 \\ \hline \end{array}$$

EVs

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \text{ only } 2$$

$$J = \begin{array}{|c|c|} \hline -2 & 1 \\ \hline -2 & 4 \\ \hline \end{array}$$

matrices NOT similar.

Strang Appendix B p. 454

consider  $J = \begin{bmatrix} 8 & 1 & & & \\ 0 & 8 & & & \\ & & 0 & 1 & \\ & & 0 & 0 & \\ & & & & 0 \end{bmatrix}$

 $\lambda=8$  is double EW

only single EV

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \hat{e}_1$$

triple  $\lambda=0$ 

$$2 \text{ EVs } \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} = \hat{e}_2 \text{ and } \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} = \hat{e}_3$$

For some  $5 \times 5$  matrix  $A$ , when will there exist  $M \ni M^{-1}AM = J$ ? one requirement is same EVsWe need vectors  $x_1, x_2, x_3, x_4, x_5 \ni$ 

$$A \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ x_1 & x_2 & x_3 & x_4 & x_5 \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ x_1 & x_2 & x_3 & x_4 & x_5 \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix} \begin{array}{|c|c|} \hline 8 & 1 \\ \hline 8 & \\ \hline & 0 & 1 \\ & 0 & 0 \\ \hline & & 0 \end{array}$$

$$\Rightarrow A\vec{x}_1 = 8\vec{x}_1 \quad | \quad A\vec{x}_2 = 8\vec{x}_2 + \vec{x}_1 \quad | \quad A\vec{x}_3 = 0\vec{x}_3 \quad | \quad A\vec{x}_4 = 0\vec{x}_4 + \vec{x}_3 \quad | \quad A\vec{x}_5 = 0\vec{x}_5$$

So we have 3 genuine EVs  $x_1, x_3, x_5$ There must be 2 "generalized EVs"  $\vec{x}_2, \vec{x}_4$  $x_2$  belongs to a "string of vectors" headed by  $x_1$ In general to find  $J$  we must search for these strings of vectors

Strang gives Filipov's Jordan form pf, which I shall skip.