

6.1 Calculus Detour - Minima, Maxima, Saddle pts are determined by a quadratic form.

Strang considers 2 fns: a general non-linear $F: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$(x,y) \mapsto 7 + 2(x+y)^2 - y \sin y - x^3$$

and a quadratic $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$(x,y) \mapsto 2x^2 + 4xy + y^2 = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 2 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x^T A x$$

Both of these have a critical pt at 0: $D^2 F_{(0,0)} = 0 = D^2 f_{(0,0)}$

And the 2nd derivs are the same:

$$D^2 F_{(0,0)} = \begin{bmatrix} 4 & 4 \\ 4 & 2 \end{bmatrix} = D^2 f_{(0,0)}$$

Remark: $D^2 f = 2A$
See my sheets for M&T ch 4.2

Strang asserts that the quadratic part of the Taylor series expansion dominates in the nbd of a critical pt [cf M&T ch 4.2 sheets and more than in G&P] and thus determines maxima and minima.

▷ so we are led to consider $f(x,y) := ax^2 + 2bxy + cy^2 = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$

What conds on a, b, c would guarantee f always pos when $\{x,y\} \neq \{0,0\}$?

Note A is symm, but more on that later.

Just plug in $\langle 1,0 \rangle$ and you see we require $a > 0$ [Likewise $\langle 0,1 \rangle$ shows $c > 0$ but we will get that for free momentarily]

Write f as the sum of 2 squares by completing the square:

$$\begin{aligned} f(x,y) = ax^2 + 2bxy + cy^2 &= a \left(x^2 + \frac{2b}{a} xy \right) + cy^2 \\ &= a \left(x^2 + \frac{2b}{a} xy + \frac{b^2}{a^2} y^2 \right) - \frac{b^2}{a} y^2 + cy^2 \\ &= a \left(x + \frac{b}{a} y \right)^2 + \left(c - \frac{b^2}{a} \right) y^2 \end{aligned}$$

This is always pos if $a > 0$

This is pos if $c - \frac{b^2}{a} > 0 \Rightarrow c > \frac{b^2}{a}$
i.e. $ac - b^2 > 0 \quad \det(A) > 0$

So f is obviously a min at (0,0) if f always pos away from origin.

Note also that $g := -f$ would have a max at (0,0) and the conds would become

$$(a) = -a \text{ always neg}$$

$$(ac - b^2) = (-a)(-c) - (-b)^2 = ac - b^2 > 0 \text{ Same}$$

Strang decides he will not consider the very degenerate case $D^2 f = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ or even $\det A = 0$. But $\det A < 0$ is allowed and that corresponds to a saddle pt like for $f(x,y) = x^2 - y^2$ [More on this later.]

▷ Now for the general quadratic $f: \mathbb{R}^n \rightarrow \mathbb{R}$

Def A is positive definite if $x^T A x > 0 \quad \forall x \neq 0$

To have no mixed terms, only $x^2 y^2 z^2$ means A is diag.

Strang considers only Symmetric matrices A when he says pos definite. There can be others,

like $A = \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$ but it is not nec to consider them because any quad form $x^T B x = x^T A x$

where B non-symm and A symm matrix. I will establish these claims on next page →

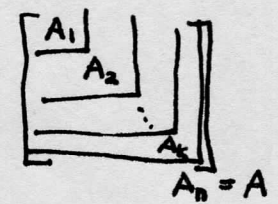
▷ Show $\begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$ is pos def: $[x \ y] \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 2x^2 + 1xy + 3y^2 > 0 \quad \forall xy \neq 0$
 because $xy < 2x^2 + 3y^2$
 To see this, for pos $a, b \ a \neq b \ 0 < (b-a)^2 = b^2 - 2ab + a^2$
 $2ab < a^2 + b^2$

Thus $xy \leq |x||y| < 2|x||y| < x^2 + y^2 < 2x^2 + 3y^2$
Claim: For any non symm square B such that $f(x) = x^T B x$, \exists symm A such that $x^T B x = x^T A x$. [Marsden & Tromba ch 4.2 sheets]

pf fix i, j . Then $x_i x_j = x_j x_i$ so $x_i x_j b_{ij} + x_j x_i b_{ji} = x_i x_j (b_{ij} + b_{ji})$
 $= x_i x_j \left(\underbrace{\frac{(b_{ij} + b_{ji})}{2}}_{a_{ij}} + \underbrace{\frac{(b_{ij} + b_{ji})}{2}}_{a_{ji}} \right)$

ch 6.2

Thm A symm pos def
 T.F.A.E. (I) $x^T A x > 0 \quad \forall x \neq 0$
 \Leftrightarrow (II) All EWs λ of A satisfy $\lambda > 0$
 \Leftrightarrow (III) All upper left submatrices A_k have $\det(A_k) > 0$
 \Leftrightarrow (IV) All pivots satisfy $d_i > 0$ (with no row exchanges)
 \Leftrightarrow (V) \exists matrix R with LI cols $\exists A = R^T R$



pf (I) \Rightarrow (II) Let $Ax = \lambda x$ where $\|x\| = 1$. Then $0 < x^T A x = x^T \lambda x = \lambda$ \square

(I) \Leftarrow (II) Since A symm, Spectral Thm says there is a basis for \mathbb{R}^n of O.N. EVs $\{x_1, \dots, x_n\}$

For any vector u , $u = \sum_{i=1}^n c_i x_i$
 $Au = c_1 A x_1 + \dots + c_n A x_n = c_1 \lambda_1 x_1 + \dots + c_n \lambda_n x_n$
 $u^T A u = (c_1 x_1^T + \dots + c_n x_n^T)(c_1 \lambda_1 x_1 + \dots + c_n \lambda_n x_n) \stackrel{\text{O.N.}}{=} c_1^2 \lambda_1 + \dots + c_n^2 \lambda_n > 0$ \square

(I) \Rightarrow (III) we can isolate submatrices from the upper left corner (elt a_{ii}) by using vectors with only the leading elts non-zero:
 choose any $k \in \{1, \dots, n-1\}$

$$\underbrace{\begin{bmatrix} u^1 & u^2 & \dots & u^k & 0 & \dots & 0 \end{bmatrix}}_{\vec{u}_k} \begin{bmatrix} A_k & * \\ * & * \end{bmatrix} \begin{bmatrix} u^1 \\ \vdots \\ u^k \\ 0 \\ \vdots \\ 0 \end{bmatrix} = u_k^T A_k u_k > 0 \text{ by (I)}$$

All EWs $\lambda_i^{(k)}$ of A_k are pos by (II)
 det is product of EWs
 $\Rightarrow \det A_k = \lambda_1^{(k)} \dots \lambda_k^{(k)} > 0$

Remarks: There is nothing special about upper left submats.
 Any chain of principal submats would work, starting at any a_{ii} on main diag and growing by adding a row and column pair each time.
 \Rightarrow this does show that a rec cond for pos def is all main diag elts pos.

cont'd \rightarrow

(III) \Rightarrow (IV) From ch 4 section 4 we know $\det A_k = d_1 \cdot d_2 \cdots d_k$ a priori, a pivot is not zero

Then $d_k = \frac{(d_1 \cdot d_2 \cdots d_{k-1}) \cdot d_k}{(d_1 \cdot d_2 \cdots d_{k-1})} = \frac{\det A_k}{\det A_{k-1}} > 0 \Rightarrow d_k \text{ pos } \forall k$

(IV) \Rightarrow (I) since A is symm, $A = LDL^T$ where D is diag matrix of pivots.

$x^T A x = x^T (LDL^T) x = (x^T L) D (L^T x)$
 $= d_1 ((L^T x)^{(1)})^2 + d_2 ((L^T x)^{(2)})^2 + \dots + d_n ((L^T x)^{(n)})^2$

This is always pos, since each d_i pos.

(I) \Leftarrow (V) $A = R^T R$ where R has LI columns

$x^T A x = x^T R^T R x = \|R x\|_2^2 > 0$ if $x \neq 0$

and we know $R x \neq 0$ if $x \neq 0$ because R has LI cols $\Rightarrow \ker(R) = \{0\}$

(I) \Rightarrow (V) There are many valid choices for R

$A = LDL^T = \underbrace{(L D^{1/2})}_{R^T} \underbrace{(D^{1/2} L^T)}_R$ or $A = Q \Lambda Q^T$ Spectral Thm
 $= (Q \Lambda^{1/2}) (\Lambda^{1/2} Q^T)$
 $R^T \quad R$

and R can be rectangular if we like:

Take any valid square R (as found above) as a matrix $Q = \begin{bmatrix} \\ \\ \end{bmatrix}$ with O.N. cols

Rectangular $R := QR$

then $R^T R = R^T [Q^T] [Q] R = R^T R = A$

In ch 3.4 we studied linear Least Sq and Normal eqs

$(A^T A) \bar{x} = A^T b$

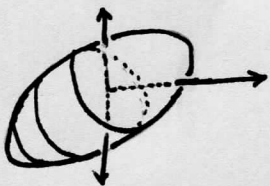
$A^T A$ is symm $\xrightarrow{\text{Spectral}}$ \exists full set of O.N. EVs β_1, \dots, β_n

$A^T A q_j = \lambda_j q_j \Rightarrow q_j^T A^T A q_j = \lambda_j q_j^T q_j \Rightarrow 0 \leq \|A q_j\|_2^2 = \lambda_j$

This is now known to be symm pos def.

Ellipsoids in n-dim

Thm Let A be symm pos def
 $\mathcal{E} := \{ \text{all } x \in \mathbb{R}^n \mid x^T A x = 1 \}$



- ① \mathcal{E} is n-dim ellipsoid
- ② The EVs of A correspond to the axes of \mathcal{E} and the EWs define the lengths of these axes inside \mathcal{E} ; the i^{th} axes of \mathcal{E} has length $\frac{1}{\sqrt{\lambda_i}}$
- ③ a rotation matrix Q would rotate \mathcal{E} to align with the co-ord axes [or phrase it as a COV $y = Q^T x$ aligns \mathcal{E}]

Pf Since A is symm, by Spectral Thm \exists O.N. matrix Q such that $A = Q \Lambda Q^T$. Define COV $y = Q^T x$
 $x = Q y$

$1 = x^T A x = y^T Q^T A Q y = y^T \Lambda y = \lambda_1 y_1^2 + \lambda_2 y_2^2 + \dots + \lambda_n y_n^2$

A pos def \Rightarrow all EWs λ are pos \Rightarrow This is the canonical eq of an ellipsoid.

Cont'd \rightarrow

The cols of Q are EVs of A .

Fix i . Plug in 0 for all y values except y_i : $0 + 0 + \dots + \lambda_i y_i^2 + 0 = 1$
 $\Rightarrow y_i = \pm \frac{1}{\sqrt{\lambda_i}}$ $\lambda_i > 0$
 length of i "semi axis" is $\frac{1}{\sqrt{\lambda_i}}$ (4)

Finally, to show Q is a rotation:

We already know Q is O.N. so $\det Q = \pm 1$.

If $+1$ we are done since that is def of rotation. If $\det Q = -1$, replace the first col $\hat{q}_1 \rightsquigarrow -\hat{q}_1$, $\tilde{Q} = \begin{bmatrix} -\hat{q}_1 & \hat{q}_2 & \dots & \hat{q}_n \end{bmatrix}$ then $\det \tilde{Q} = +1$ and since $A(-\hat{q}_1) = \lambda(-\hat{q}_1)$, this new matrix \tilde{Q} works for all the other steps \square

Remark: If A were not pos def, we could get other quadric surfaces like paraboloids, hyperboloids, etc depending on signs of EVs and if any would be 0.

(6.2.4) If A symm pos def, so is A^2, A^{-1} (in fact A^p) because $\lambda \rightsquigarrow \lambda^p$ always pos if λ is.
 (6.2.5) If A, B symm pos def, so is $A+B$ because $x^T(A+B)x = x^T A x + x^T B x > 0$

(6.2.8) A symm pos def, C n.sing $\Rightarrow B = C^T A C$ is symm pos def (special case of Sylvester's Law of Inertia)
 • $B^T = (C^T A C)^T = C^T A^T C = C^T A C = B$ ✓
 • For any $y \neq 0$, $y^T B y = y^T C^T A C y = (C y)^T A (C y) > 0$ because $C y \neq 0$ n.sing.

(6.2.9) If A symm pos def, Cauchy-Schwartz generalizes to $|\langle x, A y \rangle|^2 \leq \langle x, A x \rangle \langle y, A y \rangle$

We know $A = R^T R$

i.e. $|x^T A y|^2 \leq x^T A x y^T A y$
 $|x^T A y|^2 = |x^T R^T R y|^2 = |(R x)^T R y|^2 \stackrel{\text{regular CS}}{=} (R x)^T R x (R y)^T R y = x^T R^T R x y^T R^T R y = x^T A x y^T A y \quad \square$

Ch 6.3 Semi def and Indefinite matrices Also $Ax = \lambda Mx$

- Now we want to generalize prev Thm on pos def matrices to pos semi def
- Prove Sylvester's Law of Inertia: Signs of EVs match signs of pivots
- Introduce generalized EW problem: $Ax = \lambda Mx$

Thm 6E A symm pos Semidef [cf Thm ch 6.2]

- TFAE (I') $x^T A x \geq 0 \quad \forall x$
- (II') All EWS satisfy $\lambda \geq 0$
- (III') All principal submatrices have $\det(A_k) \geq 0$
- (IV') All pivots satisfy $d_i \geq 0$
- (V') \exists matrix R , possibly with LD cols, $\exists A = R^T R$

Pf (I') \Rightarrow (II') same as before: if $Ax = \lambda x$, take $\|x\|=1$ $0 \leq x^T A x = x^T \lambda x = \lambda$
 (I') \Leftarrow (II') Same as before: A symm $\xrightarrow{\text{Spectral}}$ $A = Q \Lambda Q^T$ $y := Q^T x$
 $x^T A x = x^T Q \Lambda Q^T x = y^T \Lambda y = \sum \lambda_i y_i^2 \geq 0$ since each $\lambda_i \geq 0$
 [if A nsing, no $\lambda=0$ so to get semi-def A must be Sing.]

(I') \Leftarrow (V') $A = R^T R$ but cols of R not nec LI
 $x^T A x = x^T R^T R x = \|R x\|_2^2 \geq 0$ since $Rx=0$ possibly even when $x \neq 0$

(I') \Rightarrow (V') same as before, I'll just give one possibility $A = Q \Lambda Q^T$ Spectral
 $= (Q \Lambda^{1/2})(\Lambda^{1/2} Q^T)$
 $= R^T R$

Strang sketches an arg for (III') and (IV') similar to the prev thm, but it involves row exchanges and is not entirely clear. He also gives a homotopy arg to derive II', III', IV' from prev thm:

Let $A(\epsilon) := A + \epsilon I$ $A(\epsilon)$ is in fact symm pos def because $x^T A_\epsilon x = x^T A x + \epsilon \|x\|^2 \geq 0 > 0$

(II') $A(\epsilon)$ has pos $\lambda_i(\epsilon)$ for all $\epsilon > 0$ and $\lambda(\epsilon)$ is a smooth fn of ϵ since
 $\det[(A + \epsilon I) - \lambda I] = 0$ is smooth poly in elts of $A(\epsilon)$

$\lim_{\epsilon \rightarrow 0} \lambda_i(\epsilon) = \lambda_i \geq 0$

(III') $\det(A_k(\epsilon)) > 0 \Rightarrow \det(A_k) = \lim_{\epsilon \rightarrow 0} [\det(A_k(\epsilon))] \geq 0$

(IV') Same idea for pivots: $d_i(\epsilon) > 0 \Rightarrow \lim \Rightarrow d_i \geq 0$

Thm 6E A symm pos Semidef [cf Thm ch 6.2]

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 $x^T A x = x^T Q \Lambda Q^T x = y^T \Lambda y = \sum_{i=1}^n \lambda_i y_i^2 \geq 0$ since each $\lambda_i \geq 0$
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Let $A(\epsilon) := A + \epsilon I$ $A(\epsilon)$ is in fact symm pos def because $x^T A_\epsilon x = x^T A x + \epsilon \|x\|_2^2 \geq 0 > 0$

(II') $A(\epsilon)$ has pos $\lambda_i(\epsilon)$ for all $\epsilon > 0$ and $\lambda_i(\epsilon)$ is a smooth fn of ϵ since

$\det[(A + \epsilon I) - \lambda I] = 0$ is smooth poly in elts of $A(\epsilon)$

$$\lim_{\epsilon \rightarrow 0} \lambda_i(\epsilon) = \lambda_i \geq 0$$

(III') $\det(A_k(\epsilon)) > 0 \implies \det(A_k) = \lim_{\epsilon \rightarrow 0} [\det(A_k(\epsilon))] \geq 0$

(IV') Same idea for pivots: $d_i(\epsilon) > 0 \implies \lim \Rightarrow d_i \geq 0$

▷ What are the elementary operations and invariants associated with a quadratic form $g(x) = x^T A x$?

Given a nsing matrix C , we consider COV $x = Cy$ which gives us the

Congruence transform $A \mapsto C^T A C$

Symmetry is preserved: $(C^T A C)^T = C^T A^T C = C^T A C$

Thm Sylvester's Law of Inertia

A symm $\implies C^T A C$ has the same 'signature' as A
 Same number of pos, neg, and 0 EWs

$n \times n$ matrices C nsing

Pf Case 1 A is nsing (no zero EWs)

IDEA: we will define a homotopy from A to $C^T A C$. But for this to work, we actually need the homotopy $Q^T A Q \rightsquigarrow C^T A C$ where Q is an ON matrix we will find.

Step 1 By Gram-Schmidt we can factorize $C = QR$ Q ON, R upper triang with strictly pos elts on main diag

Define $C_t := (1-t)Q + tQR$ $t \in [0,1]$
 $= Q [(1-t)I + tR]$

This matrix is nsing because it is upper triang with strictly pos elts on main diag
 $[(1-t)1 + t\|a_j\|]$ is always pos

Thus $\forall t \in [0,1]$ C_t is nsing.

$\implies \det > 0 \implies$ nsing
 $C_0 = Q$ $C_1 = QR = C$

Step 2 Define $B_t := C_t^T A C_t$ then $B_0 = Q^T A Q$ and $B_1 = C^T A C$

For each value of t , B_t is nsing. EWs are smooth fns of t since $\det[B_t - \lambda I] = 0$ is a poly

Step 3 A has p pos and r neg EWs

$Q^T A Q = Q^T A Q$ has exactly the same EWs, since similar matrices have same EWs.

$B_0 = Q^T A Q$

For all $t \in [0,1]$ B_t is nsing, thus even though each EW $\lambda_i(t)$ of B_t may move with t , none can touch 0, much less cross over it.

$B_1 = C^T A C \leftarrow$ so this has same number p of pos EWs and r neg EWs \square

Case 2 A singular - Strang says to work with nsing $A + \epsilon I$ and $A - \epsilon I$ and at the end let $\epsilon \rightarrow 0$

[I will give Strang's other pf on sheet 8] which does not use homotopy, just algebra. \square

COR A symm \Rightarrow Signature of pivots matches signature of EWs
 $A = LDL^T$ $A = Q^T \Lambda Q^T$

Pf we know Gaussian elimination gives us $A = LDU$ where L is lower triang and has all 1's on main diag $\Rightarrow \det = 1 \Rightarrow$ invertible.
 To get $A = LDL^T$ (which is not exactly Cholesky) observe $A^T = U^T D^T L^T$ and symm $A = A^T \Rightarrow U = L^T$

step 2 $A = LDL^T \Leftrightarrow L^{-1} A L^{-T} = D$
 Define $C := (L^{-1})^T$ then $C^T A C = D$ and we can apply Sylvester LOI to conclude A and D have same sig. D is matrix of pivots \square

\triangleright Now Strang gives a partial example of finding EWs by Givens's method using these ideas. Actually Givens does rotations to make a matrix tridiagonal and here we start with A already tri-diag.

$A = \begin{bmatrix} 3 & 3 & 0 \\ 3 & 10 & 7 \\ 0 & 7 & 8 \end{bmatrix}$ Find pivots by Gaussian Elimination
 $R_2 \rightsquigarrow R_2 - R_1 = R_2'$
 $R_3 \rightsquigarrow R_3 - R_2'$

$\begin{bmatrix} 3 & 3 & 0 \\ 0 & 7 & 7 \\ 0 & 0 & 1 \end{bmatrix}$ so $D = \begin{bmatrix} 3 & & \\ & 7 & \\ & & 1 \end{bmatrix}$ all pos elts

Guess: Is $\lambda = 2$ an EW? we would form $\det[A - 2I] \stackrel{!}{=} 0$ to check, but Strang wants to

compute pivots: $A - 2I = \begin{bmatrix} 1 & 3 & 0 \\ 3 & 8 & 7 \\ 0 & 7 & 6 \end{bmatrix}$ $R_2 \rightsquigarrow R_2 - 3R_1$
 $R_3 \rightsquigarrow R_3 - 7R_2'$ $\begin{bmatrix} 1 & 3 & 0 \\ 0 & -1 & 7 \\ 0 & 6 & 54 \end{bmatrix}$ 1 neg pivot
 This violates Sylvester so rule out $\lambda = 2$

Try $\lambda = 1 \rightsquigarrow$ again neg pivot

$\lambda = \frac{1}{2} \xrightarrow{\text{pnb 6.35}}$ pivots = $\{2.5, 59, -0.81\}$ again neg pivot

Keep going by bisection method to approx the EW

$A = A - 0I$ so we know it is between $(0, \frac{1}{2}) \dots$ (between endpoints of this interval)

algebraic pf of Sylvester's Law of Inertia (problems 6.3.6 and 6.3.7 out of order)

Lemma If domain of A has a basis of EVs $\{u_1, \dots, u_n\}$ and u_1, \dots, u_r are associated with EW $\lambda = 0$ \Rightarrow $\{u_1, \dots, u_r\}$ are a basis for $\ker(A)$ so $\dim(\ker(A)) = r$
 Any $w = \sum_{i=r+1}^n \alpha_i u_i$ is NOT in $\ker(A)$

Pf. For $u = \sum_{i=1}^r \alpha_i u_i$ $A(u) = \sum \alpha_i A(u_i) = \sum \alpha_i 0 u_i = 0$
 For $w = \sum_{i=r+1}^n \alpha_i u_i$ $A(w) = \sum \alpha_i A(u_i) = \sum \alpha_i \lambda_i u_i \neq 0$ because $\{u_i\}_{r+1}^n$ is LI
 all $\alpha_i \neq 0$ □

Lemma 2 $\text{rank}(A) = \text{rank}(C^T A C)$ C n.sing, A symm
 Equivalently A has the same number of 0 EWs (multiplicity) as $C^T A C$

Pf. We will show $\dim(\ker(A)) = \dim(\ker(C^T A C))$ rank + nullity = n
 Domain of A has EV basis $\{b_1, \dots, b_n\}$ and since C is n.sing, there is a basis $\{s_1, \dots, s_n\} \ni C s_i = b_i$. If the basis for $\ker(A)$ is b_1, \dots, b_r , then $C^T A C s_i = C^T A b_i = C^T 0 = 0 \forall i=1, \dots, r$
 so $\dim(\ker(C^T A C)) \geq \dim(\ker(A))$.
 Can any other vector w not in $\text{span}\{s_1, \dots, s_r\}$ be in $\ker(C^T A C)$? $w = \sum_{i=r+1}^n \alpha_i s_i$ $Cw = \sum_{i=r+1}^n \alpha_i b_i$
 and from first lemma $A(\sum_{i=r+1}^n \alpha_i b_i) \neq 0$ □

So now we have only to show that A and $C^T A C$ have same numbers of pos and neg EWs. Both matrices are symm, so both have ON bases.

Let $\{x_1, \dots, x_p\}$ be the ON EVs of A assoc with λ_i pos
 $\{y_1, \dots, y_q\}$ " " " " " $C^T A C$ " " μ_i neg

Step 1 show $\{x_1, \dots, x_p, y_1, \dots, y_q\}$ are LI.
 Suppose not: if LD, then $\sum a_i x_i + \sum (-b_j) y_j = 0 \Rightarrow \sum_{i=1}^p a_i x_i = \sum_{j=1}^q b_j y_j$ Call this common vector z

AND $z^T A z \geq 0$ because $Az = \sum a_i (\lambda_i x_i)$ and $z^T A z = \sum \lambda_i a_i^2 \geq 0$ since $x_i \cdot x_j = 0$ o.n.
 $z^T A z \leq 0$ because $Az = \sum b_j \mu_j y_j$ because $C^T A C y = \mu y \Rightarrow A C y = \mu C^T y$

$$z^T A z = \mu_1 b_1^2 y_1^T C^T C^T y_1 + \mu_2 b_2^2 y_2^T C^T C^T y_2 + \dots$$

$$= \mu_1 b_1^2 1 + \mu_2 b_2^2 + \dots + \mu_q b_q^2 \leq 0 \text{ because each } \mu_i \text{ neg.}$$

$z^T A z = 0$ but this requires every $a_i = 0, b_j = 0 \Rightarrow \{x_1, \dots, x_p, y_1, \dots, y_q\}$ is LI.

Step 2 $\{x_1, \dots, x_p, y_1, \dots, y_q\}$ LI in $\mathbb{R}^n \Rightarrow p + q \leq n$

Step 3 Apply same arg to $(n-p)$ neg λ_i 's and $(n-q)$ pos μ_j 's. $\Rightarrow (n-p) + (n-q) \leq n$
 $\Rightarrow n \leq p + q$

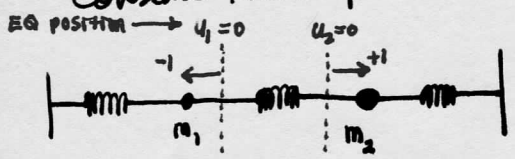
This combined with prev step shows $p + q = n \Rightarrow n - p = q$ so same # pos EWs!
 $n - q = p$ " " " neg "

Schuams LA Thm 12.4, 12.5 uses basically this same pf, but without EVs since they don't have Spectral Thm yet.

QED

Generalized EW Problem $Ax = \lambda x$ becomes $Ax = \lambda Mx$ and we want A & M both Symm.

Consider mass pts in a lattice of springs governed by Hooke's Law $F = -kx$
 $m\ddot{x} = -kx$



Unequal masses lead to M matrix
 here $m_1 = 1$ $m_2 = 2$

$$\begin{aligned} m_1 \ddot{u}_1 &= \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \\ m_2 \ddot{u}_2 &= \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \\ \begin{bmatrix} m_1 & \\ & m_2 \end{bmatrix} \begin{bmatrix} \ddot{u}_1 \\ \ddot{u}_2 \end{bmatrix} &= \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \end{aligned}$$

Assume soln $\vec{u} = e^{i\omega t} \vec{x}$
 like p.284 ch 5.4

$$\begin{aligned} \dot{u} &= i\omega e^{i\omega t} \vec{x} \\ \ddot{u} &= (i\omega)^2 e^{i\omega t} \vec{x} \\ &= -\omega^2 e^{i\omega t} \vec{x} \end{aligned}$$

$$\begin{aligned} M \ddot{u} &= A u \\ M (-\omega^2) e^{i\omega t} \vec{x} &= A e^{i\omega t} \vec{x} \\ M \lambda \vec{x} &= A \vec{x} \Rightarrow A \vec{x} = \lambda M \vec{x} \\ A \vec{x} - \lambda M \vec{x} &= 0 \\ (A - \lambda M) \vec{x} &= 0 \end{aligned}$$

So we solve $\det(A - \lambda M) = 0$
 Here $\det \begin{bmatrix} -2-\lambda & 1 \\ 1 & -2-2\lambda \end{bmatrix} = 0$ EVs give normal modes of oscillation.

Now if M is assumed Symm Pos def $M = R^T R \Rightarrow A \vec{x} = \lambda R^T R \vec{x}$

$$C := R^{-1} \Rightarrow C^T A C \vec{y} = \lambda \vec{y} \text{ with COV } \vec{y} = R \vec{x}$$

The properties of symm $C^T A C$ lead directly to corresp props for $A \vec{x} = \lambda M \vec{x}$

1. EWs are Real
2. Same signs for EWs by Sylvester LOI.
3. EVs of $C^T A C$ are ON \Rightarrow EVs of A are 'M-O.N.' $\vec{x}_i^T M \vec{x}_j = \delta_{ij}$
4. $\vec{x}_i^T A \vec{x}_j = \lambda_j \vec{x}_i^T M \vec{x}_j = \begin{cases} \lambda_j \\ 0 \end{cases}$
 Matrices A & M are being simultaneously diagonalized.

$$S = \begin{bmatrix} | & & | \\ \vec{x}_1 & \dots & \vec{x}_n \\ | & & | \end{bmatrix} \Rightarrow \begin{aligned} S^T A S &= \Lambda \\ S^T M S &= I \end{aligned}$$

Not S^{-1} ; not similarity transform

Strang says hard to visualize in general. In pos def case, $\vec{x}^T A \vec{x} = 1$ $\vec{x}^T M \vec{x} = 1$ are ellipsoids

$\vec{x} = S \vec{z}$ gives COV that makes them correctly aligned (not a pure rotation)
 S not ON

$$\begin{aligned} \vec{x}^T A \vec{x} &= \vec{z}^T S^T A S \vec{z} = \sum \lambda_j z_j^2 = 1 \\ \vec{x}^T M \vec{x} &= \sum z_j^2 = 1 \text{ sphere.} \end{aligned}$$

Minimum Principles and Rayleigh Quotient

Find a minimum principle that yields $Ax=b$ and then one that yields $Ax=\lambda x$. In 1-dim $p(x) = \frac{1}{2}ax^2 - bx$ $p'(x) = ax - b \stackrel{!}{=} 0$ $p''(x) = a$
 parabola a pos \Rightarrow
concave up
 \Rightarrow minimum

n-dim: We want to find a paraboloid P which has a minimizing pt x that is found by $Ax=b$

Given A, b define $P_{A,b}: \mathbb{R}^n \rightarrow \mathbb{R}$
 $x \mapsto \frac{1}{2}x^T Ax - x^T b = \frac{1}{2}x^T (Ax - 2b)$ Paraboloid in $\mathbb{R}^n \times \mathbb{R}$

Thm If A symm pos def $\Rightarrow P$ attains its min at x^* where $Ax^* = b$
 The min value is $P(x^*) = -\frac{1}{2}b^T A^{-1}b$

Pf. Let x^* be soln to $Ax=b$. Let $y \in \mathbb{R}^n$ arb pt. not x^*

$$P(y) - P(x^*) = \frac{1}{2}y^T Ay - y^T b - \left[\frac{1}{2}x^{*T} Ax^* - x^{*T} b \right]$$

$$= \frac{1}{2}y^T Ay - y^T Ax^* - \underbrace{\frac{1}{2}x^{*T} Ax^* + x^{*T} Ax^*}_{\frac{1}{2}x^{*T} Ax^*} = \frac{1}{2}(y-x)^T A(y-x) > 0$$

Since A pos def and $y \neq x$

$\Rightarrow P(y) - P(x^*) > 0$ for all $y \neq x^*$
 $\Rightarrow P(y) > P(x^*)$ and thus x^* is the minimizer. □

(6.4.4) Another quadratic that has minimum for $Ax=b$ is $q(x) = \frac{1}{2}\|Ax-b\|_2^2 = \frac{1}{2}x^T A^T Ax - x^T A^T b + \frac{1}{2}b^T b$

We discussed this in ch 3.2 sheets ['Linear Alg with OG' sheet 2]

$Dq_x(h) = 2x^T (A^T A)h - h^T A^T b - b^T Ah \stackrel{!}{=} 0$ for extrema

$x^T (A^T A)h = b^T Ah$ for any h

$\Rightarrow A^T Ax = A^T b$ Normal Eqs

Remark In my sheets on Quadratics, I have 2 examples of paraboloids

elliptic: $\frac{1}{\alpha^2}x^2 + \frac{1}{\beta^2}y^2 = cz$ $c > 0$

hyperbolic: $\frac{1}{\alpha^2}x^2 - \frac{1}{\beta^2}y^2 = cz$ this is saddle point

Now lets consider $Ax = \lambda x$

Define Rayleigh Quotient

$$R_A: \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}$$

$$x \mapsto \frac{x^T A x}{x^T x}$$

This is really $S^{n-1} \rightarrow \mathbb{R}$
 $\hat{x} \mapsto \hat{x}^T A \hat{x}$
 unit vectors - pts on unit sphere.

Thm Rayleigh Prince

A symm (not nec pos def)
 EWs (Real) $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$
 Corresponding EVs x_1, \dots, x_n

$\Rightarrow R_A$ is minimized by x_1
 $R_A(x_1) = \lambda_1$ (smallest EW)
 [maximized by x_n $R(x_n) = \lambda_n$]

Pf. By Spectral Thm $\Lambda = Q^T A Q$. and COV $x = Qy$ (does not change lengths)

$$\text{Then } R(x) = \frac{(Qy)^T A Qy}{(Qy)^T Qy} = \frac{y^T \Lambda y}{y^T y} = \frac{\lambda_1 y_1^2 + \lambda_2 y_2^2 + \dots + \lambda_n y_n^2}{\sum y_i^2}$$

Since $\lambda_1 \leq \lambda_i$ for $i=2, \dots, n$ $\lambda_1 (y_1^2 + y_2^2 + \dots + y_n^2) \leq \lambda_1 y_1^2 + \lambda_2 y_2^2 + \dots + \lambda_n y_n^2$

$$\Rightarrow \lambda_1 = \frac{\lambda_1 (\sum y_i^2)}{\sum y_i^2} \leq \frac{\sum \lambda_i y_i^2}{\sum y_i^2} = R(x) \quad \text{and } R(x_1) = x_1^T \lambda_1 x_1 = \lambda_1$$

$$\Rightarrow \lambda_1 = R(x_1) \leq R(x)$$

\triangleright By same arg $R(x) \leq R(x_n) = \lambda_n$ □

Thus we could numerically search for EWs by minimizing or maximizing $\frac{x^T A x}{x^T x}$; I don't know if this is ever done in practice.

Lemma Some computations we will need: $x^T \Lambda x = \sum \lambda_i x_i^2$

$$x^T Q \Lambda Q^T x = \sum \lambda_i (q_i^T x)^2$$

This refers to the case $x \in \mathbb{C}^n$, A Hermitian, U unitary $\rightarrow x^H U \Lambda U^H x = \sum \lambda_i |u_i^H x|^2$

$$x^T \Lambda x = [x_1 \ x_2 \ x_3] \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$= [x_1 \ x_2 \ x_3] \begin{bmatrix} \lambda_1 x_1 \\ \lambda_2 x_2 \\ \lambda_3 x_3 \end{bmatrix}$$

$$= \lambda_1 x_1^2 + \lambda_2 x_2^2 + \lambda_3 x_3^2$$

$$x^T Q \Lambda Q^T x = \begin{bmatrix} -\lambda_1 q_1^T x \\ -\lambda_2 q_2^T x \\ -\lambda_3 q_3^T x \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$= \begin{bmatrix} \lambda_1 q_1^T x \\ \lambda_2 q_2^T x \\ \lambda_3 q_3^T x \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

and $x^T Q = (Q^T x)^T$

$$= \begin{bmatrix} q_1^T x \\ q_2^T x \\ q_3^T x \end{bmatrix}^T$$

$$\Rightarrow \begin{bmatrix} q_1^T x & q_2^T x & q_3^T x \end{bmatrix} \begin{bmatrix} \lambda_1 q_1^T x \\ \lambda_2 q_2^T x \\ \lambda_3 q_3^T x \end{bmatrix}$$

$$= \sum \lambda_i (q_i^T x)^2 \quad \square$$

$$U \Lambda U^H = \begin{bmatrix} | & | & | \\ u_1 & u_2 & u_3 \\ | & | & | \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{bmatrix} \begin{bmatrix} -\bar{u}_1 \\ -\bar{u}_2 \\ -\bar{u}_3 \end{bmatrix} = \begin{bmatrix} | & | & | \\ u_1 & u_2 & u_3 \\ | & | & | \end{bmatrix} \begin{bmatrix} -\lambda_1 \bar{u}_1 \\ -\lambda_2 \bar{u}_2 \\ -\lambda_3 \bar{u}_3 \end{bmatrix}$$

Thm A Symm

EWs ordered $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$

$$\Rightarrow \min_{\substack{\|x\|=1 \\ x \perp \text{Span}(q_1, \dots, q_{k-1})}} \{x^T A x\} = \lambda_k$$

Horn & Johnson MA
p.177-178

This requires us to know
EVs already, so not
too useful.

$$\max_{\substack{\|x\|=1 \\ x \perp \text{Span}(q_n, \dots, q_{n-k+1})}} \{x^T A x\} = \lambda_{n-k}$$

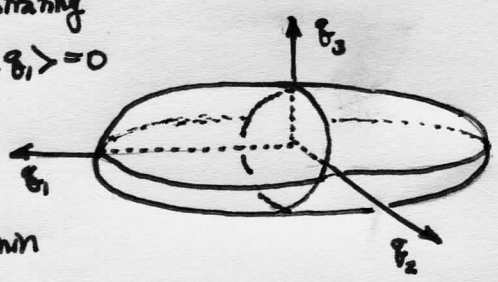
Pf Lets just consider $x \perp \text{span}\{q_1\}$ i.e. $\langle x, q_1 \rangle = 0$

$$x^T A x = x^T Q \Lambda Q^T x \stackrel{\text{lemma}}{=} \sum_{i=1}^n \lambda_i (q_i^T x)^2 = \sum_2 \lambda_i (q_i^T x)^2 \text{ because } \langle x, q_1 \rangle = 0$$

$$\geq \lambda_2 \sum_2 (q_i^T x)^2 \xrightarrow{\text{also}} \lambda_2 \sum_1 [(Q^T x)_i]^2 = \lambda_2 \|Q^T x\|_2^2 = \lambda_2 \|x\|_2^2 = \lambda_2 \cdot 1 \quad \square$$

For pos $\alpha, \beta, \gamma > 0$
 $\lambda_2 \leq \lambda_3 \leq \lambda_4$
 $\alpha \lambda_2 + \beta \lambda_3 + \gamma \lambda_4 \geq \lambda_2 \alpha + \lambda_2 \beta + \lambda_2 \gamma$

Strang p.351 is illustrating
how restricting to $\langle x, q_1 \rangle = 0$
is cutting the original
ellipsoid with a plane
and now we are
looking at the max and min
axes of that.



▷ We want to recast the above thm to avoid needing to know the EVs. I am taking
this argument from Horn & Johnson MA p.178-180 so I am switching to \mathbb{C}^n and $A = A^H$

Fix any $w \in \mathbb{C}^n$. $\sup_{\substack{\text{all } x \text{ satisfying} \\ \|x\|=1 \\ \langle x, w \rangle = 0}} \{x^H A x\} = \sup_{\substack{\|x\|=1 \\ \langle x, w \rangle = 0}} x^H U \Lambda U^H x$

let $z := U^H x \rightarrow x = Uz$
then $x^H x = (Uz)^H Uz = z^H U^H U z = z^H z \Rightarrow \|x\|=1 \Rightarrow \|z\|=1$

$$= \sup_{\substack{\|z\|=1 \\ \langle z, U^H w \rangle = 0}} \sum \lambda_i |z_i|^2$$

$$= \sup_{\substack{\|z\|=1 \\ \langle z, U^H w \rangle = 0}} \sum \lambda_i |z_i|^2$$

$$\geq \sup_{\substack{\|z\|=1 \\ \langle z, U^H w \rangle = 0 \\ z_0 = \dots = z_{n-2} = 0}} \left\{ \sum \lambda_i |z_i|^2 \right\} = \sup_{\substack{\|z\|=1 \\ \langle z, U^H w \rangle = 0}} \left\{ \lambda_{n-1} |z_{n-1}|^2 + \lambda_n |z_n|^2 \right\}$$

$$\geq \lambda_{n-1}$$

restrict to subset of \mathbb{Z}
with first $n-2$ components = 0
[Is this set empty??]

Now $|z_{n-1}|^2 + |z_n|^2 = 1$
 $\lambda_{n-1} |z_{n-1}|^2 + \lambda_n |z_n|^2 \geq \lambda_{n-1} |z_{n-1}|^2 + \lambda_{n-1} |z_n|^2$ since $\lambda_{n-1} \leq \lambda_n$
 $= \lambda_{n-1} (1)$

Thus we have shown, for any given \vec{w}

$$\sup_{\substack{|x|=1 \\ \langle x, w \rangle = 0}} \{x^H A x\} \geq \lambda_{n-1}$$

By **Spectral Thm** there is Unitary EV matrix U where $A u_k = \lambda_k u_k$

Thus $u_{n-1}^H A u_{n-1} = u_{n-1}^H \lambda_{n-1} u_{n-1} = \lambda_{n-1}$ so equality is obtained

$$\inf_{\text{all } w} \left[\sup_{\substack{|x|=1 \\ \langle x, w \rangle = 0}} x^H A x \right] = \lambda_{n-1}$$

'inf' can become 'min'.

This are generalized to

Courant-Fischer min-max Thm

A Herm
 $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$

$$\min_{\text{all tuples } \vec{w}_1, \dots, \vec{w}_{n-k}} \left[\max_{x \perp W} \frac{x^H A x}{x^H x} \right] = \lambda_k$$

$W = \text{Span} \{w_1, \dots, w_{n-k}\}$

$$\max_{\text{all } \vec{w}_1, \dots, \vec{w}_{n-k}} \left[\min_{x \perp W} \frac{x^H A x}{x^H x} \right] = \lambda_k$$

Horn p.181

Thm (Weyl) A, B Hermitian

order EVs: $\lambda_1(A) \leq \lambda_2(A) \leq \dots \leq \lambda_n(A)$
 $\lambda_1(B) \leq \dots \leq \lambda_n(B)$
 $\lambda_1(A+B) \leq \dots \leq \lambda_n(A+B)$

$$\lambda_k(A) + \lambda_1(B) \leq \lambda_k(A+B) \leq \lambda_k(A) + \lambda_n(B)$$

Pf. For any $x \in \mathbb{C}^n$ we have $\lambda_1(B) \leq \frac{x^H B x}{x^H x} \leq \lambda_n(B)$

For any $k=1, \dots, n$ we have

$$\begin{aligned} \lambda_k(A+B) &= \min_{\vec{w}_1, \dots, \vec{w}_{n-k}} \left[\max_{x \perp W} \frac{x^H (A+B) x}{x^H x} \right] \\ &= \min \left[\max_{x \perp W} \frac{x^H A x}{x^H x} + \frac{x^H B x}{x^H x} \right] \\ &\geq \min \left[\max_{x \perp W} \frac{x^H A x}{x^H x} + \lambda_1(B) \right] \\ &= \lambda_k(A) + \lambda_1(B) \end{aligned}$$

□

Cor If B pos def $\lambda_k(A+B) \geq \lambda_k(A)$

Just subtracting a pos quantity from smaller side.

This solves Strang (6.4.8) (6.4.7)

NEXT: Strang has Finite Element Method