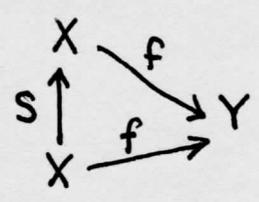


# Math Symmetry

## The Symmetry Principle



$$f: X \rightarrow Y \quad S: X \rightarrow X$$

$$f(Sx) = f(x) \quad \forall x \quad [f \text{ invariant under } S]$$

$$f(x^*) = r \quad x^* \text{ is soln}$$

$$\Sigma = f^{-1}(r) \text{ set of solutions}$$

$\Rightarrow$

$$f(S(x^*)) = r$$

so  $x^*$  is a soln  $\Rightarrow$   
 $Sx^*$  is a soln

Thus  $S(\Sigma) = \Sigma$   
(the set of solns is mapped to itself by S)

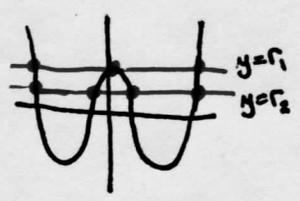
- If the soln is known to be unique, then  $Sx^* = x^*$  ( $x^* \in \text{Fix}(S)$ ) This can enable us to know some properties of  $x^*$  by its invariance under S.

**NOTE** If  $f(Sx) = f(x) \quad \forall x$   
then  $f(S(Sx)) = f(Sx) = f(x)$   
Thus for any  $k \geq 0 \quad f(S^k(x)) = f(x)$   
If  $S^{-1}$  exists, let  $y = S^{-1}(x)$   
Then  $f(Sy) = f(y)$

$f(x) = f(SS^{-1}(x)) = f(S^{-1}(x))$  Thus the Sym holds  $\forall S^k \in \langle S \rangle$  cyclic group generated by S  
 $S^0 = I$

[ Nothing said about S being a linear map yet although usually we choose such an S ]

(ex) consider an even poly  $f: \mathbb{R} \rightarrow \mathbb{R}$   
 $x \mapsto ax^6 + bx^4 + cx^2$



We seek to solve  $f(x) = r$  [ This looks like a horiz line  $y=r$  cutting the graph ]

$f$  is invariant under the reflection  $S(x) = -x \quad S: \mathbb{R} \rightarrow \mathbb{R}$   
 $f(S(x)) = a(-x)^6 + b(-x)^4 + c(-x)^2 = f(x)$

Then if  $f(x^*) = r$  so does  $f(Sx^*) = f(-x^*) = r$  [ soln  $x^* \Rightarrow$  soln  $-x^*$  ]  
 $S(\Sigma) = \Sigma$   
A given  $x^*$  is not mapped to itself unless  $x^* = -x^*$  i.e.  $x^* = 0$  as shown on  $y=r$

[ odd polys coming up later ]

(ex)  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$   
 $(x,y) \mapsto x^2 + y^2 \quad x^2 + y^2 = R^2$

This is invariant under the set of maps  $S_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$  Actually, I just have rotations here:  $SO(2)$   
This is the Lie Group  $O(2)$

$f(S_\theta(x,y)) = f(x,y)$

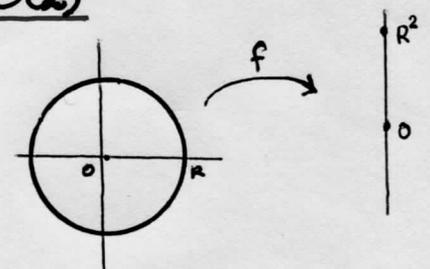
$$\begin{bmatrix} c & -s \\ s & c \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} cx - sy \\ sx + cy \end{bmatrix}$$

$$(cx - sy)^2 + (sx + cy)^2$$

$$= c^2x^2 - 2csxy + s^2y^2 + s^2x^2 + 2csxy + c^2y^2$$

$$= (c^2 + s^2)x^2 + (c^2 + s^2)y^2$$

$$= x^2 + y^2$$



The solution set  $\Sigma = f^{-1}(R^2)$  we know  $(R, 0)$  is in  $\Sigma$   
This sweeps out the set  $S_{(\theta, R)}$  for  $\theta \in [0, 2\pi]$

$S_\theta x^* = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} R \\ 0 \end{bmatrix} = \begin{bmatrix} R \cos \theta \\ R \sin \theta \end{bmatrix}$   
This gives an explicit picture of the solns  $f^{-1}(R^2)$  based on the Sym of the eq.

Equivariant Sym  $f: X \rightarrow X, S: X \rightarrow X$

more restrictive

$$S^{-1} \circ f \circ S(x) = f(x) \quad \forall x \quad [\text{i.e. } f \circ S = S \circ f]$$

$$f(x^*) = r \quad \text{where } r \in \text{Fix}(S)$$



$x^*$  is <sup>any</sup> a soln

$\Rightarrow Sx^*$  also soln

$$\Rightarrow S(\Sigma) = \Sigma$$

Pf if  $f(x^*) = r$  then  $S^{-1} \circ f \circ S(x^*) = f(x^*) = r$

$$\Rightarrow f(Sx^*) = S(r) = r \quad \text{iff } r \in \text{Fix}(S)$$

$\Rightarrow f(Sx^*) = r$  so for any soln  $x^*$ ,  $Sx^*$  is also a soln  $\square$

Again if  $f \circ S = S \circ f$  then  $f \circ S^k = S^k \circ f$  because  $f \circ S(Sx) = S \circ f(Sx) = S^2 f(x)$

For inverses if  $y = S^{-1}x$   $fSy = Sf y$  i.e.  $fSS^{-1}x = SfS^{-1}x$

$$f(x) = SfS^{-1}(x)$$

$$S^{-1} \circ f(x) = f \circ S^{-1}(x)$$

all of cyclic group  $\langle S \rangle$  commutes with  $f$

of course, this holds if  $x \in \text{Fix}(S)$

(ex)  $f: \mathbb{R} \rightarrow \mathbb{R}$  odd degree poly - all terms  
 $x \mapsto ax^5 + bx^3 + cx$

$$S(x) = -x \quad S: \mathbb{R} \rightarrow \mathbb{R}$$

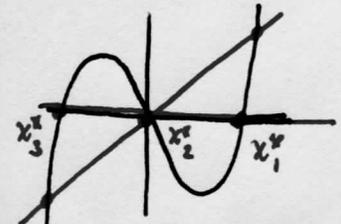
$$f(Sx) = a(-x)^5 + b(-x)^3 + c(-x) = -f(x) = S(f(x))$$

The only pt  $r$  where  $S(r) = r$  ( $-r = r$ ) is  $r = 0$

The example I drew would be more like  $x(x-2)(x+2) = x^3 - 4x$

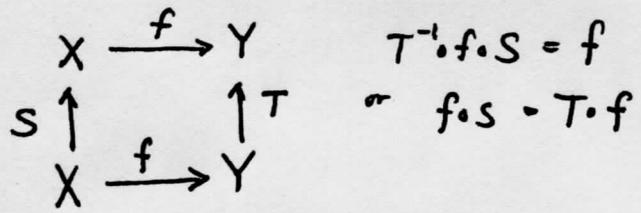
Then  $x_1^* = 2, x_2^* = 0, x_3^* = -2$   $\Sigma = \{-2, 0, 2\}$

$$S(x_i^*) = x_j^* \quad \text{but } x_2^* \text{ is FP of } S: \quad S(\Sigma) = \Sigma$$

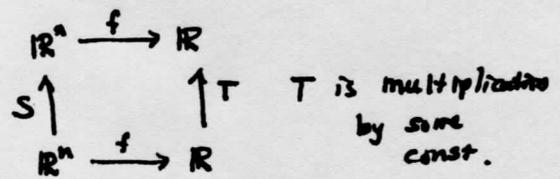


$y=mx$  There is reflection sym thru 0 but we are only using the horizontal line  $y=0$

$\triangle$  There is a more general form



commonly



We shall discuss this later

Let's look at some Sym problems found online.

(ex) This is a famous problem I saw in "Prob solving using Sym" Michael Penn youtube but also published in "Applications of Sym to Prob solving" Leitan, Berman, Zaslusky Probably the main one: Poyla Math. Discovery Part 1 p.153

No one does my Sym methods of soln

Solve this sys of eqs:  $x + 2y + 3z = 30$   
 $2x + 3y + z = 30$   
 $3x + y + 2z = 30$

$Ax = b$   
 $\begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 30 \\ 30 \\ 30 \end{bmatrix}$

Each eq defines a plane in  $\mathbb{R}^3$  we seek pts common to all i.e. their intersection

Yes  $A = A^T$  (Sym matrix) but here the Sym runs deeper

- (1) Each row is perm of same elts
- (2) special form of b - invariant under perms

Method 1 to Solve

We do note that A is nsym, so Linear Alg tells us  $\exists$  only one soln

We can interpret the problem as saying:

There is  $f: \mathbb{R}^3 \rightarrow \mathbb{R}$  and we seek  $f(x^*, y^*, z^*) = 30$   
 $\vec{x} \mapsto [1 \ 2 \ 3] \begin{bmatrix} x \\ y \\ z \end{bmatrix}$

And this f is invariant under 2 perm syms:  $f(S_{231}x) = 30 \Rightarrow [1 \ 2 \ 3] \begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 30$  (by eq 3)  
 $= [3 \ 12] \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 30$

and  $f(S_{312}x) = 30 \Rightarrow [1 \ 2 \ 3] \begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 30$  (by eq 2)  
 $= [2 \ 3 \ 1] \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 30$

NOTE: I am doing the circular perms  $1 \rightarrow 2 \rightarrow 3 \rightarrow 1$  and writing  $S_{231}$  for  $\begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} y \\ z \\ x \end{bmatrix}$  and  $S_{312}$  for  $\begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} z \\ x \\ y \end{bmatrix}$

This is not following the std convention for naming perms and their associated matrices (which would basically be the transpose of what I have) but it works [see my sheets on Abstract Alg]

since there is only 1 soln  $x^*$ , but  $S_{231}x^*$  and  $S_{312}x^*$  also satisfy the eq.  
 $\Rightarrow S_{231}x^* \stackrel{!}{=} x^*$  say  $x^* = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$  Then  $\begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} \stackrel{!}{=} \begin{bmatrix} a \\ b \\ c \end{bmatrix}$

$\begin{bmatrix} b \\ c \\ a \end{bmatrix} \stackrel{!}{=} \begin{bmatrix} a \\ b \\ c \end{bmatrix} \Rightarrow \begin{matrix} b \stackrel{!}{=} a \\ c \stackrel{!}{=} b \\ a \stackrel{!}{=} a \end{matrix}$   
 $\Rightarrow x^* = \begin{bmatrix} a \\ a \\ a \end{bmatrix}$

Now to determine the value of a:  
 $f(a, a, a) \stackrel{!}{=} 30 \Rightarrow a + 2a + 3a = 30$   
 $6a = 30$   
 $a = 5$

$x^* = \begin{bmatrix} 5 \\ 5 \\ 5 \end{bmatrix}$

Cont'd

**Method 2 to Solve**

Without affecting the soln, we can flip the last 2 eqs

$$\begin{aligned} x + 2y + 3z &= 30 \\ 3x + y + 2z &= 30 \\ 2x + 3y + z &= 30 \end{aligned}$$

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 2 & 3 & 1 \end{bmatrix}$$

This doesn't have  $A = A^T$  but it is a circulant matrix

Rename  $S_{231}$  as just  $S$ . We will show this satisfies the equivariant form  $S^{-1}AS = A$

Equivalent to show  $AS = SA$

$$\begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 2 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 1 & 2 \\ 2 & 3 & 1 \\ 1 & 2 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 2 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 1 & 2 \\ 2 & 3 & 1 \\ 1 & 2 & 3 \end{bmatrix} \checkmark$$

$$Ax = b \quad b = \begin{bmatrix} 30 \\ 30 \\ 30 \end{bmatrix}$$

$b \in \text{Fix}(S)$  so  $ASx = Sb = b$

As before we know  $\exists! x^*$  so  $Sx^* = x^*$

by same arg as prev page,  $x^* = \begin{bmatrix} a \\ a \\ a \end{bmatrix}$

and likewise we solve  $a + 2a + 3a = 30$   
 $a = 5$

▷ This also shows we have an eigenvalue eg:

$$\begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 2 & 3 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ 5 \\ 5 \end{bmatrix} = 6 \begin{bmatrix} 5 \\ 5 \\ 5 \end{bmatrix}$$

$$Ax = \lambda x$$

$$\downarrow$$

$$A(Sx) = \lambda(Sx)$$

This holds generally  
 $S^{-1}AS = A$   
 $S^{-1}ASx = Ax = \lambda x$   
 $A(Sx) = \lambda(Sx)$

▷ When would a general  $3 \times 3$  matrix satisfy  $AS = SA$  for this perm  $S$

Strong LAIA discusses this more generally ch 5

$$\begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} c & a & b \\ f & d & e \\ i & g & h \end{bmatrix}$$

whereas

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = \begin{bmatrix} d & e & f \\ g & h & i \\ a & b & c \end{bmatrix}$$

$\Rightarrow$

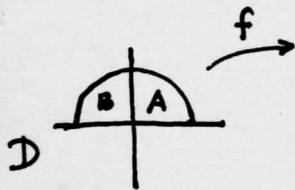
$$\begin{aligned} h &= d & i &= c \\ i &= e & g &= a \\ g &= f & a &= b \end{aligned}$$

$$\Rightarrow A = \begin{bmatrix} a & b & c \\ c & a & b \\ b & c & a \end{bmatrix}$$

Circulant

## Using Symm in Integration Problems

want to compute  $\int_D f(x) d^3x$



where we can recognize  $D = A \cup B$

and there is a map  $S$  where  $S: D \rightarrow D$   
(invariant set)

1.  $S(A) = B$
2.  $|\det DS_u| = 1$
3.  $f \circ S = f$  on  $A \cup B$   
( $f$  that respects the symm)

$$\begin{aligned} \int_{A \cup B} f(x) d^3x &= \int_A f(x) d^3x + \int_{B=S(A)} f(x) d^3x \\ &= 2 \int_A f(x) d^3x \quad \square \end{aligned}$$

$$\begin{aligned} \int_{S(A)} f(x) d^3x &\stackrel{\text{COV Thm}}{=} \int_A \underbrace{f(S(u))}_{f(u)} \underbrace{|\det DS_u|}_{1} d^3u \\ &= \int_A f(u) d^3u \quad \text{and "u" can be renamed "x".} \end{aligned}$$

we could combine (2) and (3) by

$$S^*(f dx^1 dx^2 dx^3) = f \circ S \det DS_u du^1 du^2 du^3$$

and say this is the  $f$  that respects the symm  
(but then no  $\det DS_u = -1$ ) [G&P det thm]

Sym in Integration

First let's discuss COV in integration

$$I(f, dx, (a,b)) := \int_a^b f(x) dx$$

Here is the typical case: we are given  $\int_a^b F(x) dx$  but we recognize  $F(x) = f(g(x))g'(x)$

$u := g(x)$  thus  $x \in (a,b) \Rightarrow u \in g((a,b))$  so  $\int_{x=a}^b \underbrace{f(g(x))}_u \underbrace{g'(x) dx}_{du} = \int_{g(a)}^{g(b)} f(u) du$

$$I(F, dx, (a,b)) \stackrel{\text{refactor}}{=} I(f \circ g, g'(x) dx, (a,b)) \stackrel{\text{copy the } g}{=} I(f, du, g((a,b))) \stackrel{\text{'u' is a dummy name; rename it 'x'}}{=} I(f, dx, g((a,b)))$$

so if  $g((a,b)) = (a,b)$  we have a Sym

★  $\int_a^b F(x) dx = \int_a^b f(x) dx$  same result from integrating 2 fns on same interval

▷ Consider  $\int_{-a}^a f(x) dx$  sym interval  $(-a,a)$  and Even fn  $f(-x) = f(x)$   
 Let  $S(x) = -x$  and  $f(S(x)) = f(x)$  f invariant under S

$$\int_{-a}^a f(x) dx = \int_{-a}^0 f(x) dx + \int_0^a f(x) dx$$

since  $f(S(x)) = f(x)$   $\int_{-a}^0 f(x) dx = \int_{-a}^0 f(S(x)) S'(x) dx = \int_{-a}^0 f(x) (-1) dx = - \int_{-a}^0 f(x) dx = \int_0^a f(x) dx$  and rename 'u' as 'x'  $\Rightarrow \int_0^a f(x) dx$

where we had the ingredients (1)  $S((-a,a)) = (-a,a)$  (2)  $f(S(x)) = f(x) \forall x \in (-a,a)$

$$\Rightarrow \int_{-a}^a f(x) dx = 2 \int_0^a f(x) dx$$

▷ Consider  $\int_{-a}^a f(x) dx$  : sym interval  $(-a,a)$  and Odd fn  $f(-x) = -f(x)$   
 $S(x) = -x$  but now  $f(S(x)) = -f(x) \forall x \in (-a,a)$   
f equivariant under S

$$\int_{-a}^a f(x) dx = \int_{-a}^0 f(x) dx + \int_0^a f(x) dx$$

apply COV  $\int_{-a}^0 f(x) dx = \int_{-a}^0 f(S(x)) S'(x) dx = \int_{-a}^0 -f(x) (-1) dx = \int_{-a}^0 -f(x) dx = - \int_{-a}^0 f(x) dx = \int_0^a f(x) dx$  but  $S(f(S(x))) = -f(S(x))$  so we end up with  $\int_{-a}^0 f(S(x)) S'(x) dx$  switching limits and renaming 'u'

$$\Rightarrow \int_{-a}^a f(x) dx = - \int_{-a}^0 f(x) dx + \int_0^a f(x) dx = 0$$

Here is an example using this (from youtube PrimeNumbers)

(ex)  $\int_{-3}^3 (x^5 \cos x + 1) \sqrt{9-x^2} dx$

$\underbrace{x^5}_{\text{odd}} \underbrace{(\cos x)}_{\text{even}} \underbrace{\sqrt{9-x^2}}_{\text{even}} + \underbrace{\sqrt{9-x^2}}_{\text{even}}$   
 This whole thing is odd:  $h(x) = x^5 \cos x \sqrt{9-x^2}$   
 $h(-x) = -h(x)$

$\int_{-3}^3 h(x) dx = 0$  and we only need to evaluate  $\int_{-3}^3 \sqrt{9-x^2} dx = 2 \int_0^3 \sqrt{9-x^2} dx$

Let's discuss some trickier problems, going back to (\*):  $\int_a^b F(x) dx = \int_a^b f(x) dx = cl$

This lets us do things like  $\int_a^b (F-f) dx = 0$  (if that helps)

or  $cl = \int_a^b F dx$  and  $cl = \int_a^b f dx$  so  $2cl = \int_a^b (F+f) dx$

The later case helps for a certain problem on 1987 Putnam exam

First the prototype:

$cl = \int_{-a}^a \frac{(f(x))^p}{f(x)+f(-x)} dx = \int_a^a \frac{f(-u)}{f(-u)+f(u)} (-du) = \int_{-a}^a \frac{f(-x)}{f(-x)+f(x)} dx$  (renaming 'u' as 'x')

Youtube Center of Math 'Sym in Integrals'

$cl + cl = \int_{-a}^a \frac{f^p}{f+g} + \int_{-a}^a \frac{g^p}{g+f} = \int_{-a}^a \frac{f^p+g^p}{f+g} = \int_{-a}^a 1 = a - (-a) \Rightarrow 2cl = 2a \Rightarrow cl = a$

we have domain sym and sym in the denominator

cf. youtube Let's Solve Math Problems

(ex)  $\int_{-1}^1 \frac{\sqrt{\ln(6-u)}}{\sqrt{\ln(6-u)} + \sqrt{\ln(6+u)}} du = \int_{-1}^1 \frac{f(6-u)}{f(6-u)+f(6+u)} = \int_{-1}^1 \frac{F(-u)}{F(-u)+F(u)}$

where  $F(u) = f \circ \tau_a(u) = f(-u+a)$

$\Rightarrow cl = 1$

More Generally

$cl = \int_a^b \frac{f(x)}{f(x)+f(-x+(a+b))} dx$

Reflect  $(a,b)$  to  $(-b,-a)$  by  $x \mapsto -x$   
 Translate back to  $(a,b)$  by  $x \mapsto x+(a+b)$  } This is the sym

COV  $u = -x + (a+b) \Rightarrow x = -u + (a+b)$  sym!

$x=a \Rightarrow u=b$   
 $x=b \Rightarrow u=a$   
 $dx = -du$

$\int_a^b \frac{f(-u+(a+b))}{f(-u+(a+b))+f(u)} (-du) = \int_a^b \frac{f(-x+(a+b))}{f(-x+(a+b))+f(x)} dx$  (1) we must preserve  $(a,b)$   
 (2) we must preserve denom.

rename  $\int_a^b \frac{f(x+(a+b))}{f(-x+(a+b))+f(x)} dx$

By the same trick  $2cl = b-a$  or  $cl = \frac{b-a}{2}$

(ex)  $\int_2^4 \frac{\sqrt{\ln(9-x)}(9-x)}{2\sqrt{\ln(9-x)} + \sqrt{\ln(3+x)}} dx$

$u = -x+6 \Rightarrow du = -dx$   
 $x=2 \Rightarrow u=4$   
 $x=4 \Rightarrow u=2$

$\int_2^4 \frac{f(x+3)}{f(x+3)+f(-x+9)} dx$  so  $cl = \int_2^4 \frac{f(-x+9)}{f(-x+9)+f(x+3)} dx$

and  $cl = \int_2^4 \frac{f(x+3)}{f(x+3)+f(-x+9)} dx$  (rename u as x)

Thus  $2cl = \int_2^4 1 dx = 4-2 = 2$  Thus again  $cl = 1$  This is the Putnam problem

NOT a very general technique □

Here is a related discussion, which is not really sym but a similar transform 3

youtube Channel of 'Sym in Integrals'

$$\int_0^{\infty} f(x) dx = \int_0^1 f dx + \int_1^{\infty} f dx$$

we can transform this 2<sup>nd</sup> integral to have the same domain as the 1<sup>st</sup>

$u := 1/x \quad du = -x^{-2} dx \Rightarrow dx = \frac{-1}{u^2} du$

$$\int_{x=1}^{\infty} f(x) dx = \int_{u=1}^0 f(1/u) \left(\frac{-1}{u^2} du\right) = \int_{u=0}^1 \frac{f(1/u)}{u^2} du$$

rename 'u' as 'x'  
Same domain as 1<sup>st</sup> term

$$\Rightarrow \int_0^{\infty} f(x) dx = \int_0^1 \left( f(x) + \frac{f(1/x)}{x^2} \right) dx$$

(ex)  $\int_0^{\infty} \frac{\ln x}{1+x^2} dx = \int_0^1 \frac{\ln x}{1+x^2} dx + \int_{u=1}^0 \frac{\ln(u^{-1})}{1+(1/u)^2} \left(\frac{-1}{u^2} du\right)$

$$\Rightarrow \int_0^{\infty} \frac{\ln x}{1+x^2} dx = 0$$

$\int_{u=1}^0 \frac{-\ln u}{u^2+1} (-du) = - \int_{x=0}^1 \frac{\ln x}{x^2+1} dx$

(ex)  $\int_0^{\infty} \frac{1}{(1+x^2)(1+x^\alpha)} dx = \int_0^1 \frac{1}{(1+x^2)(1+x^\alpha)} dx + \int_{u=1}^0 \frac{1}{(1+1/u^2)(1+1/u^\alpha)} \frac{-1}{u^2} du$

renaming

$$- \int_{u=1}^0 \frac{1}{(u^2+1)(\frac{u^\alpha+1}{u^\alpha})} du = \int_0^1 \frac{x^\alpha}{(x^2+1)(x^\alpha+1)} dx$$

$$= \int_0^1 \frac{1}{(1+x^2)(1+x^\alpha)} dx + \int_0^1 \frac{x^\alpha}{(1+x^2)(1+x^\alpha)} dx$$

$$= \int_0^1 \frac{\cancel{(1+x^\alpha)}}{(1+x^2)\cancel{(1+x^\alpha)}} dx = \int_0^1 \frac{1}{1+x^2} dx = \tan^{-1}(1) - \tan^{-1}(0)$$

$$= \frac{\pi}{4} - 0 = \frac{\pi}{4}$$

□

