

(1)

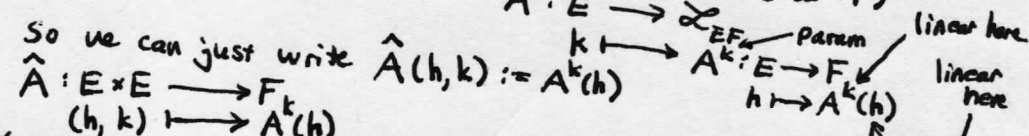
Ch 4.1 As before, consider  $f: U \rightarrow F$  then  $Df_x: E \rightarrow F$  Bdd Linear

that is to say  $Df_x \in \mathcal{L}(E \rightarrow F)$  and  $Df: U \rightarrow \mathcal{L}(E \rightarrow F)$   
 $x \mapsto Df_x(\cdot)$

then we'd have  $D^2f_x \in \mathcal{L}(E \rightarrow \mathcal{L}(E \rightarrow F))$  and  $\mathcal{L}(E \rightarrow \mathcal{L}(E \rightarrow F)) \cong \mathcal{L}(E \times E \rightarrow F)$

Canonical iso p.151

Here is that canonical iso:  $A \in \mathcal{L}(E \rightarrow \mathcal{L}(E \rightarrow F))$  that means  $A: E \rightarrow \mathcal{L}(E \rightarrow F)$  abbrev.  $\mathcal{L}^2(E \rightarrow F)$



Proceed inductively... for the next one  $A \in \mathcal{L}(E \rightarrow \mathcal{L}(E \times E \rightarrow F))$   $A: E \mapsto A^2(h,k) = \hat{A}(h,k,l)$

Back to 2<sup>nd</sup> deriv: Fix  $h \in E$ . Define  $F^h(x) := Df_x(h)$  note "F" is not v.s.  $f$ ! etc...

We seek a linear map  $A_x^h(\cdot)$  s.t.  $\|F^h(x+k) - F^h(x) - A_x^h(k)\|_F \rightarrow 0$  as  $\|k\|_E \rightarrow 0$

First we compute  $Df_x$  and give it a direction  $h: Df_x(h) =: F^h(x)$   
 Then compute  $D(F^h)_x$  and give it a direction  $k: D(F^h)_x(k)$   
 this is  $D^2f_x(h,k)$

i.e.  $\|Df_{x+k}^h - Df_x^h - A_x^h(k)\|_F \rightarrow 0$  as  $\|k\|_E \rightarrow 0$

$A_x(h,k)$  is bilinear, we name it  $D^2f_x(h,k)$   
 $D^2f$  being cont (or  $f \in C^2$ ) means  $\|x-y\| < \delta \Rightarrow \|D^2f_x - D^2f_y\| < \epsilon$   
 $\|h\| < \delta \Rightarrow \|D^2f_{x+h} - D^2f_x\| < \epsilon$

ch 4.1.2 Calculation of  $D^2f_x$

From ch 1 p.1-2  $\frac{d}{dt} f(x+th) \Big|_{t=0} = \lim_{t \rightarrow 0} \frac{1}{t} (f(x+th) - f(x)) = Df_x(h)$

Now for  $F^h(x) := Df_x(h)$

$\mathcal{J}(F^h)_x(k) = \frac{d}{ds} F^h(x+sk) \Big|_{s=0} = \frac{d}{ds} (Df_{x+sk}(h)) \Big|_{s=0}$   
 $= \frac{d}{ds} \left( \frac{d}{dt} f(x+th+sk) \Big|_{t=0} \right) \Big|_{s=0} = D^2f_x(h,k)$

The values are the same, provided the RHS exists.

order doesn't matter since we will soon show  $D^2f_x$  is sym.

See my sheets later for an example of how this is used. sheets associated with showing  $J: U \rightarrow U^{-1}$  is  $C^\infty$ .

1a

**example 1**  $f$  is linear (continuous i.e. Bdd Linear)  $f: E \rightarrow F$   
 $x \mapsto Lx$  where linear map  $L$  does not depend on  $x$ .

Then, from ch 1,  $Df_x = L$  and since there is no dependence on  $x$ ,  
 $D^n f_x \equiv 0 \quad \forall n \geq 2$

**example 2**  $f$  is bilinear  $f: E_1 \times E_2 \rightarrow F$   
 $(x_1, x_2) \mapsto b(x_1, x_2) =: B(x)$  where  $x = \langle x_1, x_2 \rangle$

Then from ch 1  $\underbrace{DB_x(h)}_{F^h(x)} = b(x_1, h_2) + b(h_1, x_2)$

To find  $D^2 B_x$  compute:

$$F^h(x+k) - F^h(x) = b(x_1+k_1, h_2) + b(h_1, x_2+k_2) - [b(x_1, h_2) + b(h_1, x_2)]$$

$$= \cancel{b(x_1, h_2)} + b(k_1, h_2) + \cancel{b(h_1, x_2)} + b(h_1, k_2) - \cancel{b(x_1, h_2)} - \cancel{b(h_1, x_2)}$$

$D^2 B(h, k) = b(k_1, h_2) + b(h_1, k_2)$

We can see this is linear in  $k$ . No dependence on  $x$ , so  $D^3 B \equiv 0, D^4 B \equiv 0, \dots$   
 This shows bilinear  $b$  is  $C^\infty$  smooth.

Here is another way:  $DB_x(h) = \underbrace{b(x_1, h_2)}_P + \underbrace{b(h_1, x_2)}_Q$

$h$  is fixed, we have 2 linear maps in  $x$ :  $P = P^{h_2} := b(\cdot, h_2)$   
 $Q = Q^{h_1} := b(h_1, \cdot)$

Then, just like for  $x \mapsto Lx$  and  $DL_x(k) = Lk$ , we have  $DP_x(k) = Pk = b(k, h_2)$   
 $DQ_x(l) = Ql = b(h_1, l)$   
 and this is the same as above.

Now we could specialize to  $E = \mathbb{R}^n$   $b(x, y) = x^T A y$  for  $n \times n$  matrix  $A$

If now  $b$  is sym:  $b(x, y) = b(y, x) \Rightarrow x^T A y = y^T A x$   $\leftarrow$  This is a scalar, so it equals its own transpose  
 $= (y^T A x)^T = x^T A^T y$

$\Rightarrow A = A^T$  Sym matrix  
 Now specialize to quadratic fcn:  $y = x$   $f(x) = b(x, x) = x^T A x$

$Df_x(h) = 2x^T A h$   
 $D^2 f_x(h, h) = b(h, h) + b(h, h) = 2b(h, h) = 2h^T A h$

Also in M&T VC ch 4.2 write-up sheets

so  $D^2 f_x(\cdot, \cdot) = 2A$

Avez DC ch4

(2)

Let's show this 2<sup>nd</sup> deriv calculation for  $f: \mathbb{R}^n \rightarrow \mathbb{R}$

[Avez doesn't do this until much later in Chapter, and no details]

Recall:  $f: \mathbb{R}^3 \rightarrow \mathbb{R}$  why is  $Df_x = \begin{bmatrix} D_1 f & D_2 f & D_3 f \\ f_x & f_y & f_z \end{bmatrix}$  ?

$f$  diff  $\Rightarrow \exists A_x: \mathbb{R}^3 \rightarrow \mathbb{R} \ni f(x+h) - f(x) = A_x h + o(h)$

Then for any basis vector  $\hat{e}_j$  let  $h = t\hat{e}_j$   $\lim_{t \rightarrow 0} \frac{1}{t} [f(x+t\hat{e}_j) - f(x)] = \lim_{t \rightarrow 0} \frac{A_x(t\hat{e}_j)}{t} = \lim_{t \rightarrow 0} \frac{A_x(t\hat{e}_j)}{t}$

say  $j=2 \hat{e}_2 \lim_{t \rightarrow 0} \frac{f(x, y+t\hat{e}_2, z) - f(x, y, z)}{t} = \begin{bmatrix} a_1^{(1)} & a_2^{(1)} & a_3^{(1)} \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

Thus we see  $\begin{bmatrix} D_1 f & D_2 f & D_3 f \end{bmatrix} = \begin{bmatrix} a_1^{(1)} & a_2^{(1)} & a_3^{(1)} \end{bmatrix}$  and  $A$  is unique, so we know this is it.

▷ Now let's apply this to 2<sup>nd</sup> deriv:

Fix  $h = \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix}$  Let  $F^h(x) := Df_x(h) = \begin{bmatrix} f_x(x) & f_y(x) & f_z(x) \end{bmatrix} \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} = \sum h_i D_i f(x) \in \mathbb{R}$

$F^h: \mathbb{R}^3 \rightarrow \mathbb{R}$   
 $x \mapsto \sum h_i D_i f(x)$  Thus  $A_x^h: \mathbb{R}^3 \rightarrow \mathbb{R}$

$A_x^h(k) = \begin{bmatrix} a_1^h(x) & a_2^h(x) & a_3^h(x) \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} D_1 F^h(x) & D_2 F^h(x) & D_3 F^h(x) \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$

$= \begin{bmatrix} D_1(\sum h_i D_i f(x)) & D_2(\sum h_i D_i f) & D_3(\sum h_i D_i f) \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$   
 $= \begin{bmatrix} \sum h_i D_1 D_i f & \sum h_i D_2 D_i f & \sum h_i D_3 D_i f \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$

$= \sum h_i \begin{bmatrix} D_1 D_i f & D_2 D_i f & D_3 D_i f \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \left( h_1 \begin{bmatrix} D_{11} & D_{21} & D_{31} \end{bmatrix} + h_2 \begin{bmatrix} D_{12} & D_{22} & D_{32} \end{bmatrix} + h_3 \begin{bmatrix} D_{13} & D_{23} & D_{33} \end{bmatrix} \right) \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$

$= [h_1 \ h_2 \ h_3] \begin{bmatrix} D_{11} f & D_{21} f & D_{31} f \\ D_{12} f & D_{22} f & D_{32} f \\ D_{13} f & D_{23} f & D_{33} f \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = D^2 f_x(h, k)$

Did I accidentally end up with transpose of matrix of partials? Usually no problem when  $D_{ij} = D_{ji} f$

□

If we had  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ , then this calculation would apply to each component  $f^{(i)}$  and we'd end up with a stack of  $m$  of these

Say  $n=2 \ m=2$

$D^2 f_x(h, k) = \begin{bmatrix} [h_1 \ h_2] \begin{bmatrix} D_{11} f^{(1)} & D_{21} f^{(1)} \\ D_{12} f^{(1)} & D_{22} f^{(1)} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} \\ [h_1 \ h_2] \begin{bmatrix} D_{11} f^{(2)} & D_{21} f^{(2)} \\ D_{12} f^{(2)} & D_{22} f^{(2)} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} \end{bmatrix}$

Thm (Schwartz)  $D^2f$  is symmetric  $D^2f_x$  exists  $\Rightarrow D^2f_x(h,k) = D^2f_x(k,h)$   
It is not nec for  $f \in C^2$  (see remarks after pf)

This is a hard and tricky Thm to prove. Avez just gives a fragment of the pf. L&S p. 188 give the whole argument, but some details are very confusing. Richard Tapia: 'Appendix E: Differentiation in Abstract Spaces' p. 19 gave the clearest argument (online document).

Pf. Fix  $x$ . We want to show  $\|D^2f_x(h,k) - D^2f_x(k,h)\| < \text{const} \cdot \varepsilon$   $\star$  call this  $\exists D^2$   
The only thing we have is: Given  $\varepsilon > 0 \exists \delta > 0 \ni |s| < \delta \Rightarrow |Df_{x+s}(\cdot) - Df_x(\cdot) - D^2f_x(\cdot, s)| < \varepsilon |s|$   
To get to  $\star$  we use the '2nd diff'  $\Delta^2f_x(h,k) = f(x+h+k) - f(x+h) - f(x+k) + f(x)$   
Note that  $\Delta^2f$  is sym in  $h,k$   
 $\star$  would become  $|\Delta^2f(h,k) - D^2f_x(h,k) - (\Delta^2f(k,h) - D^2f_x(k,h))| \leq \underbrace{|\Delta^2 - D^2|}_{(a)} + \underbrace{|\Delta^2 - D^2|}_{(b)}$

we must bound each of (a) and (b). Let's start with (a):

Step 1 Define trick fun  $G_h: [0,1] \rightarrow F$   
 $t \mapsto f(x+th+k) - f(x+th)$   
Observe that  $|\Delta^2_{hk} - D^2_{hk}| = |G_h(1) - G_h(0) - D^2f_x(h,k)| \leq \underbrace{|G_h(1) - G_h(0) - G'_h(0)|}_{\text{Bnd 1}} + \underbrace{|G'_h(0) - D^2f_x(h,k)|}_{\text{Bnd 2}}$   
Where  $G_h(1) = f(x+h+k) - f(x+h)$   
 $G_h(0) = f(x+k) - f(x)$   
 $D(G_h)_t = G'_h(t) = Df_{x+th+k}(h) - Df_{x+th}(h)$   
 $G'_h(0) = Df_{x+k}(h) - Df_x(h)$

Step 2 To work on the bounds (Bnd 1) and (Bnd 2), define a quantity:  
 $G'(t) - D^2f_x(h,k) = [Df_{x+th+k}(h) - Df_{x+th}(h) - Df_x(h) + Df_x(h) + D^2f_x(h, th-th+k)]$   
 $= [Df_{x+th+k}(h) - Df_x(h) - D^2f_x(h, th+k)] - [Df_{x+th}(h) - Df_x(h) - D^2f_x(h, th)]$   
To bound this, use the  $\exists D^2$  cond:  $0 \leq t \leq 1$   
 $|th+k| \leq |h| + |k| < \delta$  if  $|h| < \frac{1}{2}\delta$  and  $|k| < \frac{1}{2}\delta$

plug  $h$  also into the open slot in  $\exists D^2$  and get  
 $|Df_{x+th+k}(h) - Df_x(h) - D^2f_x(h, th+k)| < \varepsilon |th+k| |h| \leq \varepsilon (|h| + |k|) |h|$   
 $|Df_{x+th}(h) - Df_x(h) - D^2f_x(h, th)| < \varepsilon |th| |h| \leq \varepsilon (|h| + |k|) |h|$

Thus  $|G'(t) - D^2f_x(h,k)| \leq 2\varepsilon (|h| + |k|) |h|$   
Step 3 step 2 immediately gives us (Bnd 2):  $|G'_h(0) - D^2f_x(h,k)| \leq 2\varepsilon (|h| + |k|) |h|$

We can also bound  $|G'(t) - G'(0)| \leq |G'(t) - D^2f_x(h,k)| + |G'(0) - D^2f_x(h,k)| \leq 4\varepsilon (|h| + |k|) |h|$

This will be used for (Bnd 1) with MVT ( $\mathbb{R} \rightarrow n$  vs)

Define  $g(t) := G(t) - G'(0)t$  for  $0 \leq t \leq 1$   
Then  $g(1) = G(1) - G'(0)$   $g(0) = G(0)$   $Dg_t = G'(t) - G'(0)$   
MVT  $\Rightarrow |g(1) - g(0)| \leq \sup_{0 \leq t \leq 1} |Dg_t| (1-0) = \sup |G'(t) - G'(0)| \leq 4\varepsilon (|h| + |k|) |h|$   
 $\Rightarrow |G(1) - G(0) - G'(0)| \leq 4\varepsilon (|h| + |k|) |h|$

Step 5 plugging in for (Bnd 1) and (Bnd 2) in step 1, we see  $|\Delta^2f_x(h,k) - D^2f_x(h,k)| \leq 6\varepsilon (|h| + |k|) |h|$   
 ~~$\leq 6\varepsilon$  since  $\delta < 1$~~

Step 6 By repeating from step 1 and switching  $h$  and  $k$ , we establish (b) and thus  $\star$  next sheet

Step 7 This is not correct and requires additional argument on next page  $\rightarrow$

Schwartz Thm  $D^2f_x$  is Sym (cont'd):

First note that when we do the analogous arg for (b), we'd in fact get

$$|D^2f_x(k,h) - D^2f_x(h,k)| < 6\epsilon(|k|+|h|)|k| \leq 6\epsilon(|k|+|h|)(|k|+|h|)$$

This later bnd applies to (a) and (b)

so really  $|D^2f_x(h,k) - D^2f_x(k,h)| < 12\epsilon(|h|+|k|)^2$  provided  $|h|, |k| < \frac{1}{2}\delta_\epsilon$

To prevent  $h, k$  from depending on  $\delta$ , which depends on  $\epsilon$ , fix 2 vectors  $\bar{h}, \bar{k}$  (potentially large mag).

let  $h := t\bar{h}$   
 $k := t\bar{k}$   
 $|h| = |t\bar{h}| < \frac{\delta}{2} \Rightarrow 0 \leq t \leq \min\{\frac{1}{|\bar{h}|}\frac{\delta}{2}, \frac{1}{|\bar{k}|}\frac{\delta}{2}\}$

Then we have  $|D^2f_x(t\bar{h}, t\bar{k}) - D^2f_x(t\bar{k}, t\bar{h})| < 12\epsilon(|t\bar{h}|+|t\bar{k}|)^2 = 12t^2\epsilon \underbrace{(|\bar{h}|+|\bar{k}|)^2}_{\text{no dependence on } \epsilon}$

using bilinearity of  $D^2f_x$

$$t^2 |D^2f_x(\bar{h}, \bar{k}) - D^2f_x(\bar{k}, \bar{h})| < t^2 12\epsilon(|\bar{h}|+|\bar{k}|)^2$$

LHS holds for  $\epsilon > 0$  arb small, so we conclude  $D^2f_x(\bar{h}, \bar{k}) = D^2f_x(\bar{k}, \bar{h})$

**QED**

▷ For what could have been a counter-example, I considered a  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$  given below.

We know (cf M&T VC ch 2 sheet (15))  $f \in C^2$  at pt  $x \Rightarrow f_{xy}(x) = f_{yx}(x) \quad x = \langle x, y \rangle$

But Rudin PDMA prob 9.27 gives a pathological example where 2<sup>nd</sup> partials not cont at origin and  $f_{xy}(0) \neq f_{yx}(0) \quad [0 = \langle 0, 0 \rangle]$

Thus  $D^2f_0(h,k) = [k^1 \ k^2] \begin{bmatrix} f_{xx}(0) & f_{xy}(0) \\ f_{yx}(0) & f_{yy}(0) \end{bmatrix} \begin{bmatrix} h^1 \\ h^2 \end{bmatrix}$  would not be sym and thus contradicts thm.

The resolution is that, while the matrix of partials exists, it is not the Frechet deriv, which does not exist at 0.

$$f := \begin{cases} \frac{xy(x^2-y^2)}{x^2+y^2} & (x,y) \neq (0,0) \\ 0 & (x,y) = (0,0) \end{cases}$$

This is  $C^\infty$  smooth for pts  $x \neq 0$

[Note:  $f$  is invariant under the sym  $(x,y) \xrightarrow{S} (y,-x)$  and I discussed using this to help with the labor in my Math Symmetry sheets

$$f(x) = f(Sx) \quad Df_x = Df_{Sx} S \quad S = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$D^2f_x = S^T D^2f_{Sx} S$$

ch 4.1.5 Generalizing Schwartz' Thm

Thm  $D^n f_a$  is a sym  $n$ -linear map. i.e. Let  $\sigma$  be any perm of  $\{1, 2, \dots, n\}$

$$D^n f_a(h_1, \dots, h_n) = D^n f_a(h_{\sigma(1)}, \dots, h_{\sigma(n)})$$

pf by induction - skipped

ch 4.1.6 Calculation of  $D^n f_a$

If we know the  $n^{\text{th}}$  Frchet deriv exists, we can find its value by generalizing the procedure mentioned before:

$$D^n f_a(h_1, \dots, h_n) = \left. \frac{d}{dt_n} \dots \frac{d}{dt_1} f(a + \sum t_i h_i) \right|_{t_1=0, t_2=0, \dots, t_n=0}$$

Thm 4.3 Gateaux  $\delta^n f_x$  exists in open nbhd  $\mathcal{U}$  of  $a$   
 $\delta^n f_x \in \mathcal{L}^n(E \rightarrow F) \forall x \in \mathcal{U}$   
 $x \mapsto \delta^n f_x$  is Cont }  $\Rightarrow f$  is class  $C^n$   
 $\delta^n f_a = D^n f_a$

pf - skipped

ch 4.2 Rules for Calculation

I already showed linear and bilinear maps are  $C^\infty$  on sheet 1a

4.2.3. Leibniz bilinear prod rule: consider some operation  $*$  that is like a multiplication and bilinear in both its terms. see ch 1 sheet 7

$$f * g : E \xrightarrow{\lambda} F_1 \times F_2 \xrightarrow{b} G$$

$$x \mapsto (f(x), g(x)) \mapsto b(f(x), g(x))$$

In ch 1 sheet 7  $f * g = b \circ \lambda$   
 $D(f * g)_x = D b_{\lambda(x)} D \lambda_x$

Thm  $f, g$  of class  $C^k \Rightarrow f * g$  of class  $C^k$   
 (we can also replace  $C^k$  by  $k$ -times difb:  $C^{(k-1)+d}$ )

pf. This is essentially obvious because  $f * g = b(f, g)$  and bilinear  $b$  is  $C^\infty$   
 say  $f, g$  are  $C^1$   
 In ch 1 we found

$$D(f * g)_x(h) = \underbrace{b(Df_x(h), g(x))}_{C^0} + \underbrace{b(f(x), Dg_x(h))}_{C^1} = Df_x(h) * g + f(x) * Dg_x(h)$$

$$= F_m^h * g_m + f_m * G^h(x)$$

The LHS is  $C^0$  so  $D(f * g)$  is  $C^0$   
 $\Rightarrow f * g$  is  $C^1$

We can continue in the same way:

$$D^2(f * g)_x(h, k) = D(D(f * g)_x(h))(k) = D(F^h * g + f * G^h)$$

$$= \underbrace{b(D^2 F_x(h, k), g)}_{C^0} + \underbrace{b(F^h, D^2 g_x(k))}_{C^1} + \underbrace{b(Df_x(k), G^h)}_{C^1} + \underbrace{b(f, DG_x^h(k))}_{C^1}$$

again all terms are at least  $C^0$  so  $D^2(f * g)$  is  $C^0$ , so  $f * g$  is  $C^2$   
 and so forth for higher derivatives...  $\square$

Ch 4.2.4 Higher order derivs of a product

avez just lists so results with limited discussion, so cl shall be even more limited

consider first  $f, g$  scalar valued  $f, g: E \rightarrow K$  where  $K = \mathbb{R}$  or  $\mathbb{C}$

$$(fg)^{(n)} = \sum_{k=0}^n \binom{n}{k} f^{(n-k)} g^{(k)}$$

we can get a feel for this from

$$(fg)' = f'g + fg'$$

$$(fg)'' = f''g + f'g' + f'g' + fg'' = \binom{2}{0}f''g + \binom{2}{1}f'g' + \binom{2}{2}fg''$$

$$D^n(f*g)_x(h_1, \dots, h_n) = \sum_{k=0}^n \sum_{\mathcal{Q}} b(D^k f_x(h_{i_1}, \dots, h_{i_k}), D^{n-k} g_x(h_{j_1}, \dots, h_{j_{n-k}}))$$

where ' $\mathcal{Q}$ ' means the sum over all partitions of  $(h_1, \dots, h_n)$  into 2 subsets with indices in ascending order:  $i_1 < \dots < i_k$   
 $j_1 < \dots < j_{n-k}$

Define  $\text{Sym } A(h_1, \dots, h_n) := \frac{1}{n!} \sum_{\text{all } \sigma} A(h_{\sigma(1)}, \dots, h_{\sigma(n)})$  avg over all perms  $\sigma$  of  $\{1, \dots, n\}$

So we could write  $D^n(f*g) = \text{Sym} \left[ \sum_{k=0}^n \binom{n}{k} b(D^{n-k} f, D^k g) \right]$

Ch 4.2.5 Derivs of Composite maps

Thm 4.4  $E \xrightarrow{g} F \xrightarrow{f} G$  }  $\Rightarrow f \circ g$  is also class  $C^k$   
 $f, g$  class  $C^k$

pf by induct - skipped

They give some horrible formulas, cumulating with  
avez has  $g \circ f$   $D^n(g \circ f) = \text{Sym} \left[ \sum_{\beta=1}^n \sum_{\alpha_1+\dots+\alpha_\beta=n} \frac{n!}{\alpha_1! \dots \alpha_\beta!} D^\beta(g \circ f) (D^{\alpha_1} f, \dots, D^{\alpha_\beta} f) \right]$

I will carry out an extensive discussion of  $D^2(f \circ g)_x \rightarrow$