

The Size of the Nbdls in Inv FT

$$x_0 \in U \text{ and } f(x_0) = y_0$$

Prop 2.5.6 $f: U \xrightarrow{E} F$ C^r smooth $r \geq 2$

Df_a iso

$$\text{Define } L := \|Df_a\|, M := \|Df_a^{-1}\|$$

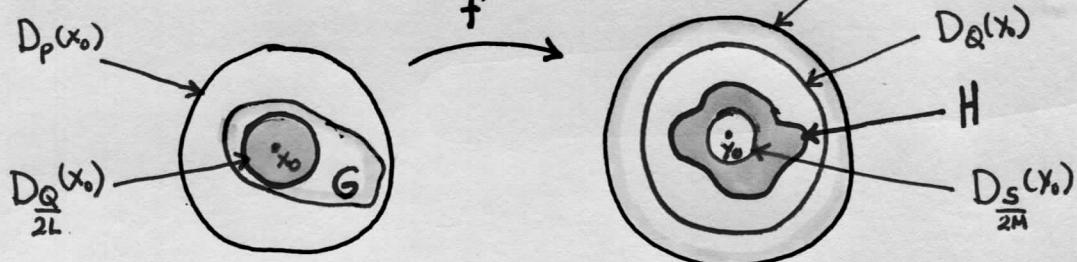
Let $\|D^2 f_x\| \leq K$ for $\|x - a\| \leq R$ and $B_R(a) \subseteq U$

$$\text{Define } P := \min\left(\frac{1}{2KM}, R\right)$$

$$Q := \min\left(\frac{1}{2NL}, M, P\right)$$

$$S := \min\left(\frac{1}{2KM}, \frac{Q}{2L}, Q\right)$$

$$N := 8M^3K$$



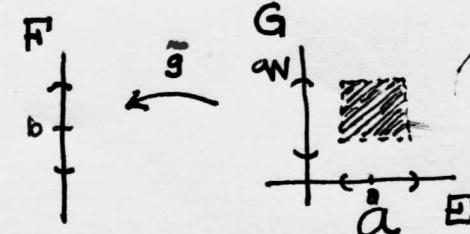
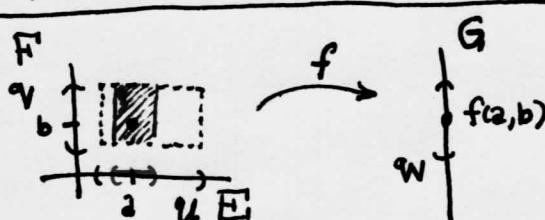
Thm 3.2 (thickening of usual Imp FT)

(Note domain is split)

$$f: \mathbb{E}^* \times \mathbb{V} \xrightarrow{\text{C}^1} G \quad \begin{matrix} E, F, G \\ \text{Banach Spaces} \end{matrix}$$

$$D_2 f_{(a,b)}: F \longrightarrow G \quad \text{iso}$$

\exists open sets $a \in A, f(a,b) \in W$
 $\exists! \tilde{g}: A \times W \xrightarrow{\text{C}^1} V \ni$
 $f(x, \tilde{g}(x,w)) = w \quad \forall (x,w) \in A \times W$
 tilde because \tilde{g} here depends on w



The shaded blue area is mapped to shaded blue area by φ

Pf: The whole idea is to construct a func $\varphi: \mathbb{E}^* \times F \longrightarrow \mathbb{E}^* \times G$
 and apply Inv FT to φ . $\varphi = \pi_1 \times f$

Step 1 Show that $D\varphi_{ab}(\langle h, k \rangle) = \langle h, D_1 f_{ab}(h) + D_2 f_{ab}(k) \rangle$

We need linear $L \ni \frac{\|\varphi(a+h, b+k) - \varphi(a, b) - L(\langle h, k \rangle)\|}{\|\langle h, k \rangle\|} \rightarrow 0_{E \times G} \quad \text{as } \|h, k\| \rightarrow 0$

$$\begin{aligned} \varphi(a+h, b+k) - \varphi(a, b) &= \langle a+h, f(a+h, b+k) \rangle - \langle a, f(a, b) \rangle \\ &= \langle h, f(a+h, b+k) - f(a, b) \rangle \end{aligned}$$

Hence we take $L(\langle h, k \rangle) := \langle h, Df_{ab}(\langle h, k \rangle) \rangle$

$$\text{Then } \frac{\|\varphi(a+h, b+k) - \varphi(a, b) - L(\langle h, k \rangle)\|}{\|\langle h, k \rangle\|} = \|\langle 0, \frac{f(a+h, b+k) - f(a, b) - Df_{ab}(\langle h, k \rangle)}{\|\langle h, k \rangle\|} \rangle\|$$

since f is diff, 2nd quantity $\rightarrow 0$

And we know from ch 1 sheet ⑧ $Df_{ab}(\langle h, k \rangle) = D_1 f_{ab}(h) + D_2 f_{ab}(k)$

Step 2 Show $D\varphi_{ab}$ is invertible by explicitly exhibiting the inverse.

We need a linear map $Q \ni \begin{cases} Q \cdot D\varphi_{ab}(\langle h, k \rangle) = \langle h, k \rangle \\ D\varphi_{ab} \cdot Q(\langle h', k' \rangle) = \langle h', k' \rangle \end{cases}$ we don't use this one

We just work with 1st component,
 $Q(\langle h, D_1 f_{ab}(h) + D_2 f_{ab}(k) \rangle) = \langle h, k \rangle \Rightarrow Q^{-1}(\langle h', k' \rangle) = \pi_1(\langle h', k' \rangle) = h'$

$$Q(\langle h, D_1 f_{ab}(h) + D_2 f_{ab}(k) \rangle) = \langle h, k \rangle \Rightarrow Q^{-1}(\langle h', k' \rangle) = \pi_1(\langle h', k' \rangle) = h'$$

For Q^{-1} , note that if $D_1 f(h) + D_2 f(k) = k' \Rightarrow k = D_2 f^{-1}(k' - D_1 f(h))$

$$\text{Thus } Q^{-1}(\langle h', k' \rangle) = D_2 f^{-1}(k' - D_1 f_{ab}(h'))$$

$$\text{Explicit formula for } (D\varphi_{ab})^{-1} = Q(\langle h', k' \rangle) = \langle h', D_2 f^{-1}(k' - D_1 f_{ab}(h')) \rangle$$

cont'd →

Step 3 Apply Inv FT to φ

$$\begin{array}{ccc} E \times F & & E \times G \\ \varphi : (\text{nbhd of } (a, b)) & \xrightarrow{\text{diffeo}} & (\text{nbhd of } (\varphi(a, b))) \\ & & \leftarrow \begin{array}{l} \text{trimming down,} \\ \text{we can write} \\ \text{this } A \times W \end{array} \end{array}$$

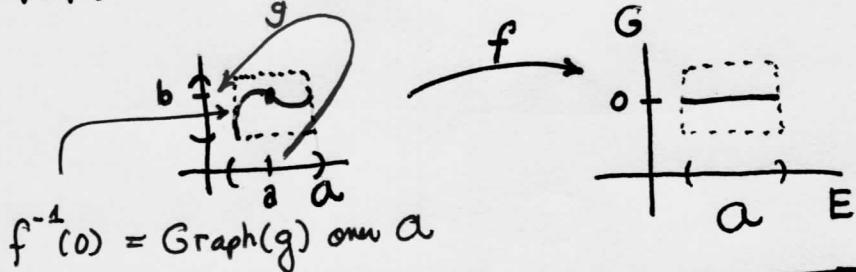
For every $(x, w) \in A \times W$ \exists pt $(x, y) \in q_1 \ni \varphi^{-1}(x, w) = (x, y)$
i.e. $(\varphi^{-1})^1(x, w) = x$ Define $\tilde{g} := (\varphi^{-1})^2$ and clearly \tilde{g} is smooth
 $(\varphi^{-1})^2(x, w) = y$ $f(x, \tilde{g}(x, w)) = w$

□

COR 3.2 Standard (Implicit Fcn Thm)

Same basic hypotheses as before. Note how domain is split

$$\left. \begin{array}{l} f: U \times V \xrightarrow{C^1} G \\ D_2 f_{ab}: F \xrightarrow{\text{iso}} G \\ f(a, b) = 0 \quad [\text{so we restrict to } w=0] \end{array} \right\} \Rightarrow \begin{array}{l} \textcircled{1} \exists! g: A \xrightarrow{C^1} B \ni f(x, g(x)) = 0 \\ \text{that is: } f^{-1}(0) = \text{Graph}(g) \text{ over } A \\ \textcircled{2} Dg_x = -D_2 f_{(x, g(x))}^{-1}(D_1 f_{(x, g(x))}) \end{array}$$



Pf. Take $g(x) := \tilde{g}(x, 0)$. Thus we have $\tilde{g}: A \times \{0\} \xrightarrow{C^1} V$

so the range is $B := \tilde{g}(A \times \{0\})$

$\forall x \in A \quad f(x, g(x)) = f(x, \tilde{g}(x, 0)) = 0$ from Thm.

And since we have $f(x, g(x)) = 0$ apply $\frac{d}{dx}$ to both sides

$$D_1 f_{(x, g(x))} + D_2 f_{(x, g(x))} Dg_x = 0 \Rightarrow D_2 f_{(x, g(x))} Dg_x = -D_1 f_{(x, g(x))}$$

But is $D_2 f_{(x, g(x))}$ invertible? We know $D_2 f_{(a, g(a))}$ is. $A := D_2 f_{ab}$

On ch 3 sheet ③ we have the Thm that Invertible linear maps form an open set.
 $\|A - B\| < \frac{1}{\|A^{-1}\|} \Rightarrow B^{-1}$ exists. We know $D_2 f_{(x, g(x))}$ is cont in x , so for x near a ,

$D_2 f_{(x, g(x))}$ is near A and thus $D_2 f_{(x, g(x))}^{-1}$ exists

$$\Rightarrow Dg_x = -D_2 f_{(x, g(x))}^{-1}(D_1 f_{(x, g(x))})$$

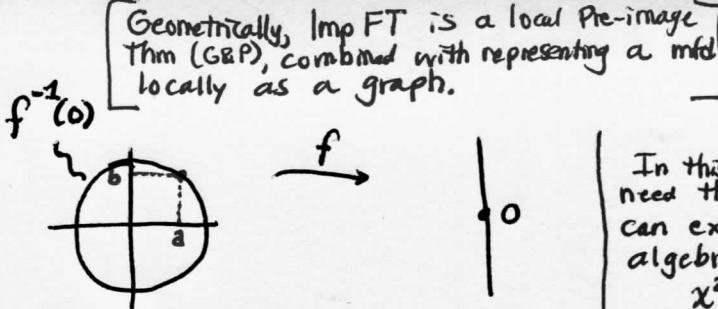
□

Let's do some examples

domain splitting

$$f: \mathbb{R}_+^1 \times \mathbb{R}_+^1 \rightarrow \mathbb{R}^1$$

$$\langle x, y \rangle \mapsto x^2 + y^2 - 1$$



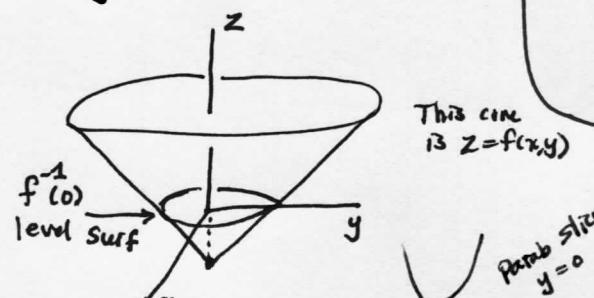
For $\langle a, b \rangle$ on the circle as shown, we have $f(a, b) = 0$
and we want a fcn $y = y(x)$ $\Rightarrow f(x, y(x)) = 0$

$$D_2 f_{ab} = \frac{\partial}{\partial y} (x^2 + y^2 - 1) \Big|_{ab} = 2y \Big|_b = 2b \neq 0 \quad \text{for } b \text{ as shown } (b \neq 0)$$

In this example, we can illustrate the geometric meaning of this
consider $z = f(x, y) = x^2 + y^2 - 1$ the graph of f .

$D_2 f \neq 0$ is saying $\frac{\partial z}{\partial y} \neq 0$

$\frac{\partial}{\partial y}$ is tangent to level surf at $\langle 1, 0 \rangle$
 $\Rightarrow \frac{\partial}{\partial y} f(1, 0) = 0$



In this example, we don't need the Imp FT, we can explicitly solve algebraically:

$$x^2 + y^2 - 1 = 0$$

$$y^2 = 1 - x^2$$

$$y_1(x) = \sqrt{1 - x^2}$$

$$y_2(x) = -\sqrt{1 - x^2}$$

We could also differentiate implicitly (Imp FT says y' exists)

$$2x + 2y y' = 0$$

$$y' = -\frac{x}{y}$$

where $y \neq 0$

This $D_2 f_{ab} \neq 0$ means
 $Df_{ab} = [f_x, f_y] \neq [0, 0]$
so $f^{-1}(0)$ is locally a submfld in nbhd of $\langle a, b \rangle$

$f^{-1}(0)$ is a level curve of $z = f(x, y)$. At pt $\langle a, b \rangle$ z is incr in both the $\frac{\partial}{\partial x} = e_1$ and $\frac{\partial}{\partial y} = e_2$ directions. But at $\langle 1, 0 \rangle$ and $\langle -1, 0 \rangle$, $\frac{\partial}{\partial y}$ is tangent to the level curve $\rightarrow f$ is not changing in that dir. Thus $\frac{\partial z}{\partial y} = \frac{\partial f}{\partial y} = D_2 f$ is 0 there.

$y(x)$ [a.k.a. $g(x)$] $\frac{dy}{dx} = -\frac{\frac{\partial z}{\partial x}}{\frac{\partial z}{\partial y}} = \frac{-\frac{\partial z}{\partial x}}{0}$ undefined (vertical slope)

[But at $\langle 1, 0 \rangle$, no problem with $x = x(y)$]

For $\langle x, y \rangle \neq \langle 1, 0 \rangle$ or $\langle -1, 0 \rangle$ the 2nd part of Imp FT gives

$$Dg_x = -D_2 f(D_x f) \quad \text{or} \quad \frac{dy}{dx} = -\left(\frac{\partial z}{\partial y}\right)\left(\frac{\partial z}{\partial x}\right) = \frac{-1}{2y} 2x = \frac{-x}{y}$$

[we could solve this ODE $y dy = -x dx \Rightarrow x^2 + y^2 = C$ but not telling us more than we know]

ex 2 Linear version (could be considered a prototype) Rudin PDMA p.224

$$A: \mathbb{R}^m \times \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$\langle x, y \rangle \mapsto A[x]$$

$$A(0, 0) = 0$$

$$\begin{bmatrix} A_1 & | & A_2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \vec{0} \Rightarrow A_1 x + A_2 y = 0 \Rightarrow A_2 y = -A_1 x$$

If A_2^{-1} exists, we can solve $y = \underbrace{-A_2^{-1}(A_1 x)}_{y(x)}$

Then $A(x, y(x)) = 0 \quad \forall x \in \mathbb{R}^m$ (global Imp FT)

$A^{-1}(0) = \ker(A)$ is a subsp of \mathbb{R}^{m+n} i.e. Submfld.
m-dim

Since $y(x)$ is linear fcn,
 $Dy_x(h) = -A_2^{-1} A_1 h$

□

Avez DC ch3

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(12)

Example from M&T ch 4
ex 10 p.242

Can we solve

$$xy^2 + xzu + yu^2 = 3$$

$$u^3yz + 2xu - u^2u^2 = 2$$

near pt

$$\langle x, y, z, u, v \rangle = \langle 1, 1, 1, 1 \rangle$$

1?
cont'd

Define $f: \mathbb{R}^3 \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$\begin{bmatrix} x \\ y \\ z \\ u \end{bmatrix} \mapsto$$

$$\begin{bmatrix} xy^2 + xzu + yu^2 - 3 \\ u^3yz + 2xu - u^2u^2 - 2 \end{bmatrix}$$

We seek solns on $f^{-1}(0)$, that is $\{ \langle x, y, z, u \rangle \mid f(x, u) = 0 \}$

Can we apply Imp FT?

$$D_2 f_a = D_{(u,v)} f = \begin{bmatrix} \frac{\partial f}{\partial u} & \frac{\partial f}{\partial v} \\ \frac{\partial f}{\partial u} & \frac{\partial f}{\partial v} \end{bmatrix} = \begin{bmatrix} xz & 2uy \\ (3u^2yz - 2u^2u^2) & (2x - 2u^2u^2) \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix}$$

$$\det(D_2 f_a) = -2 \neq 0 \text{ so } D_2 f_a \text{ is an iso}$$

Plug in
 $\langle 1, 1, 1, 1 \rangle$

By Imp FT, $\exists g: A \rightarrow B$

$$\begin{bmatrix} x, y, z \\ u, v \end{bmatrix} \mapsto \begin{bmatrix} u(x, y, z) \\ v(x, y, z) \end{bmatrix}$$

the function g exists, but we don't have an explicit form to write down.

(b) $Dg_x = -(D_2 f_{(x, g(x))})^{-1} (D_1 f_{(x, g(x))})$

Compute $D_1 f$ and evaluate at $\langle x, y, z \rangle = \langle 1, 1, 1 \rangle$

$$D_1 f = \begin{bmatrix} (y^2 + zu) & (2yz + u^2) \\ 2u & u^3z \end{bmatrix} \begin{bmatrix} xu \\ u^2y \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 3 & 1 \\ 2 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$Dg_x \Big|_{\langle 1, 1, 1 \rangle} = -\frac{1}{-2} \begin{bmatrix} 0 & -2 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 3 & 1 \\ 2 & 1 & 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -4 & -2 & -2 \\ 0 & -2 & 0 \end{bmatrix} = \begin{bmatrix} -2 & -1 & -1 \\ 0 & \textcircled{-1} & 0 \end{bmatrix}$$

This is $\frac{\partial v}{\partial y}(1, 1, 1)$

The question specifically asked for $\frac{\partial v}{\partial y}(1, 1, 1)$

M&T VC ch 4.4

we could use implicit differentiation for a slightly shorter way for a specific result like this.

Thm 3.3

$$f: \mathcal{U} \xrightarrow{\text{C}^2} F \quad \text{Banach spaces}$$

Another COR
of thickened
Imp FT
Thm 3.2

$a \in \mathcal{U}$ open set

$E = \ker(Df_a) \oplus E_2$ where E_2 is a topologically closed subspace

$$Df_a : \ker(Df_a) \oplus E_2 \xrightarrow{\text{Onto}} F \quad (\text{so Banach sp})$$

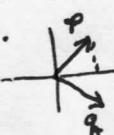
$f(\mathcal{U})$ contains an open nbhd of $f(a)$

Pf. $\ker(Df_a) = Df_a^{-1}(\{0\})$ Df_a cont, so $Df_a^{-1}(\{0\})$ is a topologically closed set.
 \Rightarrow it's a Banach sp.

We need to meet the hypotheses of Thm 3.2, so we can use it.

[Note that we don't need the hypothesis that E_2 is closed if E is fin dim,
or if E is Hilbert space, because then take $E_2 = (\ker(Df_a))^\perp$]

Remark: I wanted to say $E_2 := \{h \in E \mid Df_a(h) \neq 0\}$ but this DOES NOT WORK.
Consider $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ $\ker(A) = \text{Span}\{e_1\}$ but everything not on x-axis is NOT valid subsp
 $\vec{p} + \vec{q} \in \ker(A)$ so this candidate for E_2 is not even algebraically closed



so $E = E_1 \oplus E_2$ means any $v \in E$ has a unique representation $v = h + k$ $h \in E_1$, $k \in E_2$
we can regard v, h, k as vectors in E , or as pairs in $E_1 \oplus E_2$ as
 $v = \langle h, k \rangle$, $h = \langle h, 0 \rangle$, $k = \langle 0, k \rangle$

► The final ingredient we need is that $D_2 f_a : E_2 \rightarrow F$ is an iso

We know $D_2 f_a$ is linear

$D_2 f_a$ is One-to-One because $\ker(D_2 f_a) = \{0\}$.

To see this, let $v = \langle h, k \rangle$ $Df_a(\langle h, k \rangle) = D_1 f_a(h) + D_2 f_a(k)$

Since $E_1 = \ker(Df_a)$ $D_1 f_a(h) = 0$

Lets assume $D_2 f_a(k) = 0$ Then $Df_a(\langle h, k \rangle) = 0 + 0 = 0$
 $\Rightarrow \langle h, k \rangle \in \ker(Df_a) \Rightarrow k = 0$

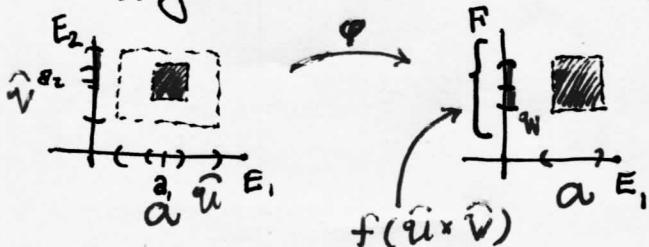
$D_2 f_a$ is Onto F because if we choose any $f \in F$

we know Df_a maps onto F so $\exists v \ni Df_a(v) = f$

$v = \langle h, k \rangle$ so $\underbrace{Df_a(\langle h, k \rangle)}_0 = f \quad \underbrace{D_1 f_a(h) + D_2 f_a(k)}_{=0} \Rightarrow D_2 f_a(k) = f$
 $D_2 f_a : E_2 \rightarrow F$

Therefore $D_2 f_a : E_2 \rightarrow F$ is iso

We can apply Thm 3.2 (thickened Imp FT)



$$f(u+v) \subseteq f(\hat{u} + \hat{v}) \subseteq f(\mathcal{U})$$

□

Now we will show that this Corollary to thickened Imp FT can be used to prove the existence of solns to ODEs:

What we will show is that the nonlinear ODE defined on $[0,1]$ by

$$u'(t) + t u^2(t) = g(t) \text{ has a soln } u \in C^1[0,1] \text{ provided } |g(t)| < \varepsilon \quad \forall t \in [0,1]$$

Following ch 1 ex 3 on sheet ② define $f: C^1[0,1] \xrightarrow{\text{E}} C^0[0,1]$

and we computed $Df_u(h) = h' + 2tuh$

$\begin{array}{c} \text{Df}_u(h) = h' + 2tuh \\ \text{Df}_0(h) = h' = \frac{d}{dt}h \quad \text{so} \quad Df_0 = \frac{d}{dt} \\ \text{Df}_0: \text{all } h \in C^1[0,1] \xrightarrow{O: t \mapsto 0} \text{Df}_0(h) \end{array}$

Df_0 maps onto $C^0[0,1]$: choose any $g \in C^0[0,1]$. $\exists G \ni G' = g$, namely

$$G(t) := \int_0^t g(s) ds$$

Split the domain:

$$\begin{aligned} E_1 &:= \ker(Df_0) = \left\{ \text{all } h \in C^1 \mid Df_0(h) = \frac{d}{dt}h = 0_{C^0} \right\} = \left\{ \text{all const fns } h(t) = c \right\} \\ E_2 &:= \left\{ \text{all } h \in C^1 \mid \int_0^1 h(t) dt = 0 \right\} \end{aligned}$$

Claim: $E = E_1 \oplus E_2$

pf: for any h , we can write $h = \underbrace{(h - c_h)}_{h_2} + \underbrace{c_h}_{h_1}$ where $c_h := \int_0^1 h(t) dt$ const which depends on h

E_2 is a topologically closed subsp because if $(h_k) \rightarrow h \in C^1$ we can show $\int_0^1 h(t) dt = 0$

Each $h_k \in E_2$, let $h_k \rightarrow h$. Is $h \in E_2$?

This E has no relation to E in the theorem

$$L > K \Rightarrow \|h_k - h\|_{C^1} < \varepsilon \text{ that means } \left(\sup_{t \in [0,1]} |h_k(t) - h(t)| + \sup_{t \in [0,1]} |h'_k(t) - h'(t)| \right) < \varepsilon$$

In particular, for any t , $|h_k(t) - h(t)| \leq \sup_{t \in [0,1]} |h_k(t) - h(t)| < \varepsilon$

Now $\left| \int_0^1 h(t) dt \right| = \left| \int_0^1 h_k(t) - \int_0^1 h(t) dt \right| \leq \int_0^1 |h_k(t) - h(t)| dt < \int_0^1 \varepsilon = \varepsilon$ but ε arb small $\Rightarrow \int_0^1 h(t) dt = 0$ \square

Now apply Thm 3.3 taking " \bar{a} " = $0_{C^1[0,1]}$

$$f(a) = f(0) = f_0 \text{ where } f_0(t) = 0'(t) + t 0^2(t) = 0_R$$

So by Thm 3.3 \exists a ball $B(f_0, \varepsilon)$ in $C^0[0,1] = F \ni g \in B(f_0, \varepsilon)$ then $g \in f(U)$

But if $g \in f(C^1[0,1])$ then $\exists u \in C^1[0,1] \ni f(u) = g$

$\{g \mid \sup_{t \in [0,1]} |g(t) - 0| < \varepsilon\}$

i.e. $f_u = g$ i.e. $u'(t) + t u^2(t) = g(t) \quad \forall t \in [0,1]$

Th3 is saying the ODE has a soln. \square