

$$\dot{X} = f(x) \quad f: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$\varphi: \mathbb{R} \rightarrow \mathbb{R}^n$ is a soln if $\dot{\varphi}(t) = f(\varphi(t)) \quad \forall t \in \mathbb{R}$.

so follow LGS ch 9 we have $g: \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}^n$
 $(t, x) \mapsto g_x(t, x) = \dot{g}(t, x) = \dot{g}_x(t)$

" g_x " is a " φ " that passes thru $p \in X$ at $t=0$; $g_x(0) = X$.

We can expand g_x in a Taylor poly. about $t_0 = 0$:

$$g_x(t) = g_x(0) + \dot{g}_x(0)(t-0) + \frac{\ddot{g}_x(\xi)}{2}(t-0)^2$$

$$\parallel \quad \parallel$$

$$g_x(t) = f(g_x(0)) + f'(g_x(0))t + O(t^2)$$

$$\Rightarrow \dot{g}_t(x) = X + f(x)t + O(t^2) \quad (\star)$$

$\nabla \cdot \dot{f}$

Thm 2 $\text{div}(f) = 0 \Rightarrow g_t$ preserves Leb μ : $V(t) = V(0)$.

pf. Let D_0 be a @able set in \mathbb{R}^n .

Lemma 1: $\dot{V}(0) = \int_{D_0} \text{div}(f) dx$ Apostol MA p. 421
COV formula

pf. By def, $V(t) := \int_{g_t(D_0)} 1 dy = \int_{D_0} |\det(Dg_x)| dx$

Now from (\star) , $d(g_t)_x = I + t \cdot df_x + O(t^2)$
 we need a Lemma to help us compute the det of this

Lemma 2: $\det(I + At) = 1 + \text{tr}(A)t + O(t^2)$

See also Aronsmith & Place AITDS p. 46 for a clever pf.

pf: From Atkinson AITNA p. 402
 $\det(A - \lambda I) = (-1)^n \lambda^n + \text{tr}(A) \lambda^{n-1} + \dots + \det(A)$
 so here $\det(A + I) = t^n \det(A + \frac{1}{t}I) \quad \lambda^i = -\frac{1}{t}$
 $\Rightarrow (-1)^n \lambda^n \det(A - \lambda I) = 1 + (-1)^n \text{tr}(A) \lambda^{n-1} + O(\lambda^2)$
 $\Rightarrow 1 + (-1)^n \text{tr}(A)t + O(t^2)$

cont'd \rightarrow



$T^*M = \mathbb{R}^2$

Let $\Phi: \mathbb{R} \times T^*M \rightarrow T^*M$ be the Hamiltonian flow and a a FP.

By def, a is asymptotically stable if given $\epsilon > 0, \exists \delta > 0, T_\epsilon \ni$

At $t=0, \forall x \in B(a, \delta), \Phi^t(x) \in B(a, \epsilon) \forall t > T_\epsilon.$

δ depends on ϵ , not $\epsilon.$
choose $\epsilon < \delta$ and we see the flow isn't volume preserving!

Nowhere could I find a clean def of Asymp Stab
That really says what I just said!
Maybe I'm wrong!!

(115)

We had
$$V(t) = \int_{D_0} |\det [dg_{t,x}]| dx$$

$$= \int_{D_0} | \det [I + t df_x + o(t^2)] | dx$$

Lemma 2.

$$\det = 1 + t \cdot \text{tr}(df_x) + o(t^2)$$

$$= \int_{D_0} | 1 + t \text{tr}[df_x] + o(t^2) | dx$$

Then $\frac{d}{dt} V(t) = \frac{d}{dt} \int_{D_0} | \det [dg_{t,x}] | dx = \int_{D_0} \frac{d}{dt} | \det [dg_{t,x}] | dx$ since integrand is continuous

$$[df_x] = \begin{bmatrix} \frac{\partial f}{\partial x^1} & \dots & \frac{\partial f}{\partial x^n} \\ \frac{\partial f}{\partial x^1} & \dots & \frac{\partial f}{\partial x^n} \end{bmatrix}$$

$$\Rightarrow \dot{V}(0) = \int_{D_0} | \text{tr}[df_x] | dx$$

$$= \int_{D_0} \left| \sum \frac{\partial f}{\partial x^i} \right| dx$$

$$= \int_{D_0} | \text{div}(f) | dx$$

END LEMMA 1 \square

\Rightarrow So if $\text{div}(f) = 0, \dot{V}(0) = 0 \Rightarrow \text{Vol } B \text{ const}$

Thm 2 \square

In the special case of Hamilton's Eqs

$$\begin{bmatrix} \dot{q}_1 \\ \vdots \\ \dot{q}_n \\ \dot{p}_1 \\ \vdots \\ \dot{p}_n \end{bmatrix} = \begin{bmatrix} \frac{\partial H}{\partial p_1} \\ \vdots \\ \frac{\partial H}{\partial p_n} \\ -\frac{\partial H}{\partial q_1} \\ \vdots \\ -\frac{\partial H}{\partial q_n} \end{bmatrix}$$

form $\dot{x} = f(x)$

$$\nabla \cdot \vec{f} = \nabla \cdot h = \sum \frac{\partial}{\partial q_i} \left(\frac{\partial H}{\partial p_i} \right) + \sum \frac{\partial}{\partial p_i} \left(-\frac{\partial H}{\partial q_i} \right)$$

= 0 since we can interchange partials

$$= \sum 0 = 0.$$

$$\text{div}(h) = 0$$

\square

R.187

ex 1



$$\begin{bmatrix} c^1(t) \\ c^2(t) \end{bmatrix} = \begin{bmatrix} \cos(t) \\ \sin(t) \end{bmatrix}$$

$$\text{Area} = \pi r^2 = \pi \cdot 1^2$$

$$\int_{C[0, 2\pi]} p \, dq = \int_0^{2\pi} c^1(t) \dot{c}^2(t) \, dt = \int_0^{2\pi} \cos(t) \cos(t) \, dt = \pi$$

ex 2 M 3-mfd in \mathbb{R}^3

$$\omega^1 = a_1 dx + a_2 dy + a_3 dz \quad [a_1, a_2, a_3]$$

$$\int_{\mathcal{C}} \omega^1 = \int_0^1 [a_1(t) \dot{x}_1(t) dt + a_2(t) \dot{x}_2(t) dt + a_3(t) \dot{x}_3(t) dt]$$

Prob 14 \mathcal{C} is a 2-chain, which would have an image like:



Presumably we can apply a version of Stokes thm

$$\int_{\mathcal{C}} p_i \, dq_i = \int_{\partial \mathcal{C}} p_i \, dq_i$$

$\partial \mathcal{C}$ is a collection of pw smooth curves, and for each curve \mathcal{C}_i we know from above that $\int_{\mathcal{C}_i} p_i \, dq_i = \text{Area of the set in } \mathcal{C}_i, \mathbb{R}^3\text{-plane that is enclosed by the projection of the image of } \mathcal{C}_i.$



we will take $\varphi = \varphi^2$ where α is a chart map.

$$\Delta: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$(t,s) \mapsto \varphi(A^t B^s x) - \varphi(B^s A^t x)$$

Really we should write $\Delta_{\varphi, x}(t,s)$ but that is too cumbersome.

" $x_1 = t$ "
" $x_2 = s$ "

$$\Delta(t,s) = \Delta(0,0) + \sum_{i=1}^2 (D_i \Delta)_{(0,0)} x_i + \frac{1}{2} \sum_{j,k=1}^2 (D_{j,k} \Delta)_{(0,0)} x_j x_k + \frac{1}{6} \sum_{j,k,l=1}^2 (D_{j,k,l} \Delta)_{(0,0)} x_j x_k x_l$$

Apostol MA p. 361 Taylor Thm

example of calculations: $\frac{\partial \Delta}{\partial t}(t,s) = T\varphi_{A(t, B^s x)} \cdot \frac{\partial A}{\partial t}(t, B^s x) - T\varphi_{B(s, A(t,x))} \cdot T(B^s)_{A(t,x)} \cdot \frac{\partial A}{\partial t}(t,x)$

Hence $\frac{\partial \Delta}{\partial t}(t,0) = T\varphi_{A(t,x)} \cdot \frac{\partial A}{\partial t}(t,x) - T\varphi_{A(t,x)} \cdot Id_{t,x} \cdot \frac{\partial A}{\partial t}(t,x) = 0$

so we see immediately $\frac{\partial \Delta}{\partial t}(0,0) = 0$ and $\frac{\partial}{\partial t} \left(\frac{\partial \Delta}{\partial t}(t,0) \right) = 0$

By symmetry, same results hold for $\frac{\partial}{\partial s}$.

Thm

(\Rightarrow) For any φ , we form $\Delta_{\varphi, x}(t,s) := \varphi(A^t B^s x) - \varphi(B^s A^t x) = 0$

then $\frac{\partial}{\partial s} \Delta(0,0) = 0 \stackrel{\text{Lemma 1}}{\Rightarrow} (L_{B^s} \varphi - L_{A^t} \varphi)(x) = 0$

$= (L_{[A,B]} \varphi)(x) = 0$

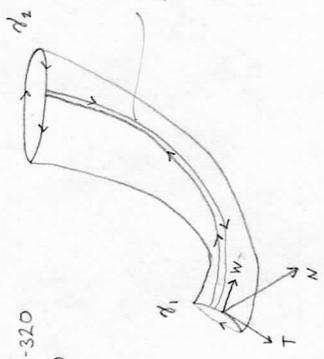
but since φ is arb, we must have $[A,B] = 0$.



5/24

Munkres AOM p. 317-320
p. 290

In my picture, γ_2 is oriented opposite of Arnold's version Fig 180



Imagined curve to help us orient γ_2 consistently w/ γ_1

Stokes Thm: $\int_M (\nabla \times F) \cdot N \, dA = \int_{\partial M} \vec{F} \cdot \vec{ds}$ also symbolized

"F" = V in Arnold's notation.

Here M is the 2-mfd defined as the set of pts in \mathbb{R}^3 that is swept out by the flowlines of $R = \text{Curl}(V)$ which pass thru γ_1

So obviously $\vec{R}_{\text{Curl}} \in T_x M$ and $\hat{N}_{\text{Curl}} \perp T_x M$
 $\Rightarrow 0 = \vec{R}_{\text{Curl}} \cdot \hat{N}_{\text{Curl}} = (\text{Curl}(V))(x) \cdot N(x)$

$$\int_M 0 \, dA = \int_{\gamma_1} V \cdot ds - \int_{\gamma_2} V \cdot ds$$

QED

Prob 2.

I think $\omega^2 = \sum_{i,j} dp^i \wedge dq^j - \omega^1 \wedge dt$ has matrix

$$\begin{bmatrix} I & & & \\ & -I & & \\ & & z & \\ & & & I \end{bmatrix}$$

clearly nonsing.

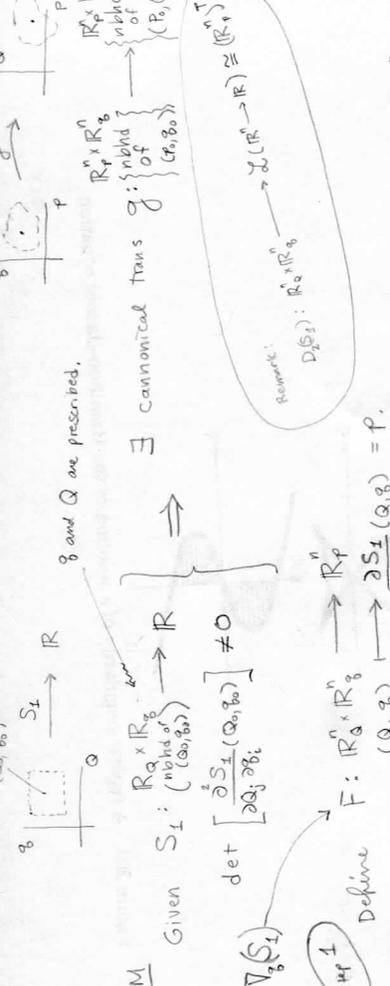
Since we later assume $d\omega^2$ is nonsing

M $(2n+1)$ -mfd
 ω^2 1-form on M .

We know from the Lemma that for every $x \in M$, $\exists!$ a vector $\xi_x \in T_x M \ni d\omega^2(\xi_x, \cdot) = 0(\cdot)$
 \Rightarrow There is a vector field $X_{\omega^2}: M \rightarrow TM \leftarrow \xi_x$ Arnold calls this the 'vortex direction'.

The streamlines of X_{ω^2} are called the 'vortex lines'.

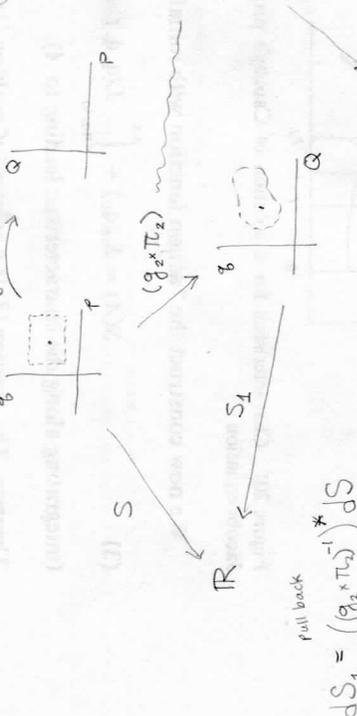
The set of pts of M that are passed thru by streamlines of X_{ω^2} originating in γ is called the "Vortex Tube of γ ".



CLAIM: If g is a Canonical Trans $\Rightarrow \det [D_1(g_2, (q_0, g_0))] \neq 0$

$\triangleright \det [D_1(g_2, (q_0, g_0))] \neq 0$

In a nbhd of (q_0, g_0) we can define a fn $S_1 \ni S_1(q, g) = S(q, g)$ AND $\frac{\partial S_1(q, g)}{\partial g} = P$



pull back $dS_1 = (g_2 \times \pi_2)^* dS$

$[D(g_2 \times \pi_2)]_{(q_0, g_0)} = \begin{bmatrix} \frac{\partial g_1}{\partial q_1} & \frac{\partial g_1}{\partial g_1} \\ 0 & I \end{bmatrix}$

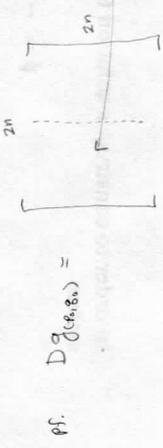
so $\det [D(g_2 \times \pi_2)]_{(q_0, g_0)} = \det \left[\frac{\partial g_1}{\partial q_1} \right] \neq 0$

Apply Inv Fcn Thm to $g_2 \times \pi_2$ and we have the result.

NOTE relevant to P. 267

In more generality, $g = [g^1, g^2, \dots, g^n]^T$. Then instead of working with $g_1 = g^1 \times \dots \times g^n$, we can work with any subset $\{i_1, \dots, i_n\} \subset \{1, \dots, 2n\}$ and have the map $(g^{i_1} \times g^{i_2} \times \dots \times g^{i_n}) : (q, g) \mapsto (P_i, Q_{i_2}, g)$

CLAIM: For at least one such index set I , $\det [D_P(h_I)]_{(q_0, g_0)} \neq 0$



$D_P(h_I)$ is a $n \times n$ submatrix chosen from n rows from this half of Dg

If every such submatrix had $\det = 0 \Rightarrow \det Dg = 0 \Rightarrow$ since g is diffeo.

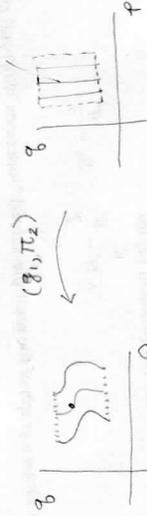
THM Given $S_1 : R^m \times R^n \rightarrow R^m$ \Rightarrow Canonical Trans $g : \text{nbhd of } (q_0, g_0) \rightarrow R^m$

$\det \left[\frac{\partial S_1}{\partial g_j} \right]_{(q_0, g_0)} \neq 0$

Define $F : R^m \times R^n \rightarrow R^m$ $\frac{\partial S_1}{\partial g} = P$

$[D_0 F(q_0, g_0)] \neq 0 \Rightarrow \det \left[\frac{\partial^2 S_1}{\partial q_i \partial g_j} \right] \neq 0$

Avez D.C p. 28 Imp Fcn Thm: \exists smooth $g_1 : \text{nbhd of } (q_0, g_0) \rightarrow R^m$



STEP 2

Now we need an expression for $P = g_2(q, g)$

Define $G : R^m \times R^n \rightarrow R^m$ $\frac{\partial S_1}{\partial g} = P$

but we can then define $P := g_2(q, g) = -D_x(S_1)(g_1, g, g)$

Then $g = (g_1, g_2) : Q \rightarrow P$ and g is a Canonical Trans because:



$\sum (P_i dq_i - P_i dQ_i) = \sum \frac{\partial S_1}{\partial g_j} dg_j + \frac{\partial S_1}{\partial Q} dQ = dS_1(q, g)$

$= dS(q, g)$

See p. 258 \square

d commutes w/ pullback

$dS = (g_1, \pi_2)^* dS_1$

The map $\langle r, g \rangle \mapsto \langle p, q \rangle$ is a CT because:

$$d(S_2)_{(r,p)} = \frac{\partial S_2}{\partial r} dr + \frac{\partial S_2}{\partial p} dp$$

$$= p dr + q dp$$

$$d(S_2 - d(PQ)) = p dr + q dp - d(PQ)$$

$$= p dr - PdQ$$

Since we have determined $P = P(r, g)$ and $Q = Q(r, g)$, S depends only on $\langle r, g \rangle$.

and therefore $dS_{(r,g)} = p dr - PdQ$ depending only on $\langle r, g \rangle$.

We want a generating fcn for $I: \langle r, g \rangle \mapsto \begin{bmatrix} p \\ q \end{bmatrix} = [P]$.

- ① $S(r, q)$
- ② $S(r, p)$
- ③ $S(g, p)$
- ④ $S(r, p)$

[an even a mixed combo of the type on p. 268, but I would consider that here.]

(1) Following p. 258 Boff, we must have $\langle r, g \rangle \mapsto \langle p, q \rangle$ a diffeo on a neighborhood of $\langle r_0, g_0 \rangle$.

$$\text{Here } D(\pi_2 \circ g_0) = \begin{bmatrix} \frac{\partial q}{\partial r} & \frac{\partial q}{\partial g} \\ \frac{\partial p}{\partial r} & \frac{\partial p}{\partial g} \end{bmatrix} = \begin{bmatrix} 0 & I \\ 0 & I \end{bmatrix} \text{ not invertible.}$$

$$\langle r, g \rangle \mapsto \begin{bmatrix} r \\ q \end{bmatrix} = g$$

$$= \begin{bmatrix} I & 0 \\ 0 & I \end{bmatrix} \text{ This works}$$

$$\langle r, g \rangle \mapsto \begin{bmatrix} r \\ p \end{bmatrix} = P$$

$$= \begin{bmatrix} I \\ I \end{bmatrix} \text{ This works}$$

$$\langle r, g \rangle \mapsto \begin{bmatrix} r \\ p \end{bmatrix} \text{ fails.}$$

So we may use $S(r, q)$ or $S(g, p)$.

For the first, a viable fcn is

$$S(r, q) = \int r dg \text{ THEN}$$

$$r_j := \frac{\partial S}{\partial r_j} = q_j$$

$$p_j := \frac{\partial S}{\partial q_j} = r_j \text{ Id}$$

$$S(r, p) = \int r_j p_j$$

$$\Rightarrow r_j := \frac{\partial S}{\partial r_j} = p_j$$

$$q_j := \frac{\partial S}{\partial p_j} = r_j \text{ Id}$$

A. 176

For some fcn S depending only on $\langle r, g \rangle$

$$\theta_1 - g^* \theta_2 = \delta S$$

KEY IDEA: we must have $\int r_j dg_j - p_j dq_j = dS_{(r,g)}$ in order for $\langle r, g \rangle \mapsto \langle p, q \rangle$ to be Canonical Trans.

▷ If we are given $S = S_1(r, q)$ then we are directly able to use the dg, dq form of $\theta_1 - g^* \theta_2$:

$$p dr - p dq = \frac{\partial S_1}{\partial r} dr - \frac{\partial S_1}{\partial q} dq$$

▷ However, if we are given $S_2(g, p)$, then

$$d(S_2)_{(g,p)} = \frac{\partial S_2}{\partial g} dg + \frac{\partial S_2}{\partial p} dp$$

So we must convert θ_1 to a form that explicitly features dg and dp [however it still must be a fcn of r, g]

By adding $d(PQ)$ to both sides in θ_1 we get

$$\theta_1 \iff p dr + q dp = d(PQ + S) = d(S_2(g, p))$$

[This could be glossing over an important detail

see Moser, p. 176 my r. 487-490 work thru Birkhoff

p. 212

Another variant of (2) is:

If \mathcal{M}_f is Conn and each X_{dF_i} is Complete v.f.

see A&M p. 113

$\Rightarrow \mathcal{M}_f$ diffeos to $T^k \times \mathbb{R}^{n-k}$

Notes on the pf of Lemma 1:

P. 211

vfs X, Y are said to commute if Lie bracket vanishes: $[X, Y] = 0$
 $[X, Y] = 0 = -[Y, X]$

Here we know that $[X_{dF_i}, X_{dF_j}] = 0$ because

$[X_{dF_i}, X_{dF_j}] = X_{d(F_i F_j)} = X_{d0} = 0$ since we have an isomorphism from space of 1-forms to v.f.s.

L&S p. 519-520

We know that \mathcal{M}_f is invariant under the flows inf generated

by the v.f.s X_{dF_i} because:

Guillemin & Pollack
Diff Top p. 24

$$\mathcal{M}_f = \sigma^{-1}(f) \quad \ker(d\sigma_x) = T_x(\mathcal{M}_f)$$

Thirring p. 108

$$dF_i(X_{dF_j}) = \underbrace{L_{X_{dF_j}}(F_i)}_{\text{Lie deriv}} = \{F_i, F_j\} = 0 \text{ since } \mathcal{M}_f \text{ is involutive.}$$

This holds $\forall i, j$

$$\Rightarrow X_{dF_i}(x) \in \ker(d\sigma_x) = T_x(\mathcal{M}_f)$$

So the flowlines are restricted to \mathcal{M}_f

□

$\Gamma_{x_0} = \{ \text{all } T \in \mathbb{R}^n \mid G_x(t) = x_0 \}$ additive subgroup of \mathbb{R}^n discrete topology.

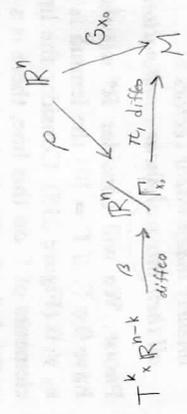
This is a group of covering transforms of \mathbb{R}^n when it acts on \mathbb{R}^n by translations.

Boothby AITMARC
P. 102 Thm 9.3

$$\theta: \Gamma_{x_0} \times \mathbb{R}^n \longrightarrow \mathbb{R}^n$$

$$(t, x) \longmapsto x + t$$

It also acts transitively on $G_{x_0}(p)$ for any $p \in M$.



Note that $\mathbb{R}^n / \mathbb{Z}^k \times \mathbb{R}^{n-k}$ is diffeomorphic to $T^k \times \mathbb{R}^{n-k}$.

$n-k$ must be zero since M is cpt.

Prob 4.1 Since $T^n = S^1 \times \dots \times S^1$ we have a canonical inverse chart, given an inverse chart for S^1 $\varphi_1: (-\epsilon, \epsilon) \rightarrow U$.

$$\text{Then } \varphi: U_1 \times \dots \times U_n \xrightarrow{p} \mathbb{R}^n \xrightarrow{\beta} \{ \varphi_1(p_1), \dots, \varphi_n(p_n) \} \text{ is a basis for } T_p(T^n)$$

$$\beta^* X_{\text{dH}} \longrightarrow \mathcal{H}_p \longrightarrow \mathcal{H}_p^*$$

we have the hamiltonian $\forall f$ X_{dH} on \mathcal{H}_p and the diffeo $\beta: T^n \rightarrow \mathcal{H}_p$. Pull it back to T^n and express it wrt basis $\{ \frac{\partial}{\partial p_i} \}$:

$$\beta^* X_{\text{dH}} = \omega_1 \frac{\partial}{\partial p_1} + \dots + \omega_n \frac{\partial}{\partial p_n}$$

$\left[\omega_i \text{ are not related to our } \mathbb{Z}^n \text{-form } \omega^2 \right]$

Then we get the cond periodic motion defined by $\dot{\varphi}_i = \omega_i; i=1, \dots, n$.

□